

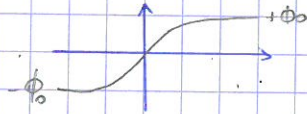
A flavor of the computation of the dynamic scaling:

$T=0 \rightarrow$  no noise:  $\frac{\partial \phi}{\partial t}(\vec{x}, t) = \nabla^2 \phi(\vec{x}, t) - \frac{\delta V}{\delta \phi(\vec{x}, t)}$

$v = -\mu_2 \phi^2 + \frac{g}{4} \phi^4$

\* trivial solution  $\phi(x, t) = \pm \phi_0 \forall x, t.$

\* finite wall



$\phi(x) = \pm \phi_0 \text{th} \sqrt{\frac{\mu}{2}}(x-0)$

ALLEN-CAHN expanded around this solution: velocity in the direction of the curvature

(only static if wall is vertical!)

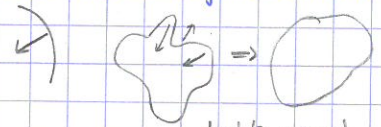
(sounds and shrinks domain:

$\frac{dA}{dt} = \frac{d(\pi R^2)}{dt} = 2\pi R \frac{dR}{dt} = -\frac{2\pi \lambda^2(t)}{2\pi} R K = -\lambda(t)$

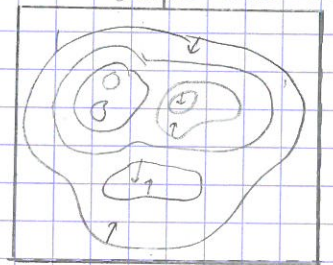
$\Rightarrow A(t) = A_0 - \lambda^2(t)t \rightarrow$  linearly vanishing (any form of domain) in 2d

$G(R(t)) \sim t^{1/2}$

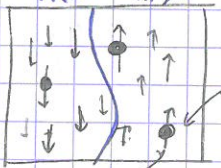
unstable  $\downarrow = -1/R$



tend to round Collapse the domain wall

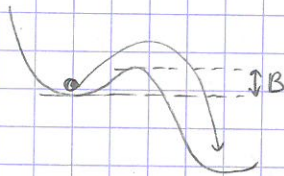


weak disorder  $h_i < 0$   $h_i > 0$



fixed spins imposing random field

$\rightarrow$  the domain wall is pinned by disorder  $\rightarrow$  hard to move



Arrhenius time scale:  $t_A \sim$  to  $e^{B/k_B T}$

$B \sim$  length of the domain wall we would like to move  $B(R)$ .

(droplet argument:  $\Delta F(R) \sim -\epsilon R^d + \epsilon_s R^{d-1}$ )

$R^* = \text{max } \Delta F(R)$  as barrier  $\rightarrow R^* \sim \frac{\epsilon_s}{\epsilon} \rightarrow \Delta F(R^*) \sim \epsilon R^{*d}$

$\rightarrow t \sim$  to  $e^{\frac{\epsilon R^{*d}}{k_B T}}$   $B(R) \sim \epsilon R^{\psi}$   $\rightarrow R = \frac{k_B T}{\epsilon} \left( \ln \frac{t}{t_0} \right)^{1/\psi}$   $\rightarrow$  much slower!

14/07/2017

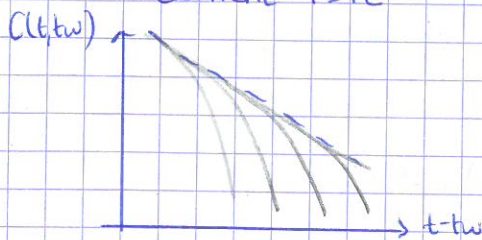
summary & discussions on coarsening systems

- 2.
- 3.

instead of looking at  $(r, t)$  we can look at the 2 time self correlations  $C(t, t_w) = \langle s_i(t) s_i(t_w) \rangle$

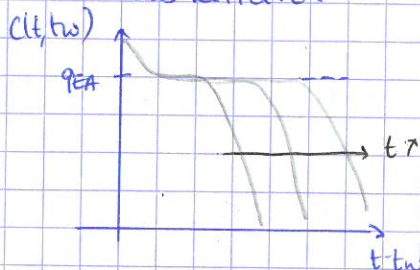
local in space  
non-local in time

(the picture is equivalent critical  $T=T_c$ )



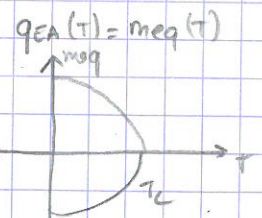
MULTIPLICATIVE

SUBCRITICAL



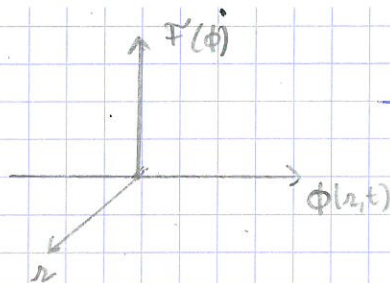
SEPARATION OF THE SCALES

$\neq 0$  ADDITIVE



still looking at  $t < t_{relax} \sim L^z$

Now if looking at the whole field  $\phi(\vec{r}, t)$



→ non trivial interpretations here, beware!

University classes according to  $R(t, T)$ :

$$R(t, T) \sim \lambda(T) t^{1/2}$$

→ issue in the computation of the scaling functions describing aging:  $f\left(\frac{R(t)}{R(t_0)}\right)$

Response functions

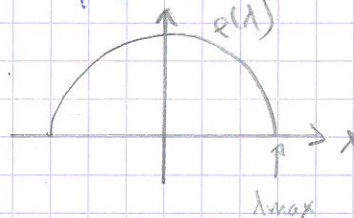
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mean field treatment of coarsening

$$H = -\sum_{ij} J_{ij} s_i s_j + z \left( \sum_i s_i^2 - N \right)$$

↓  
Lagrange multiplier  
spherical constrained  
 $s_i \in \mathbb{R}$

$J_{ij} \sim W(\nu, \Gamma) \rightarrow$  spectrum:  $\rho(\lambda_\mu) \propto \sqrt{(2J)^2 - \lambda_\mu}$



$\equiv$  harmonic oscillators constrained

↳ to decouple them  $\rightarrow$  go the eigen basis of  $J!$   $\{s_\mu\}$

$$H = -\sum_{\mu} \lambda_{\mu} s_{\mu}^2 + z \left( \sum_{\mu} s_{\mu}^2 - N \right) \rightarrow \text{only coupled via the spherical constraint}$$

$s_{\mu}(t) = F(t, z(+)) \rightarrow$  perfectly solvable problem.

Yet this problem remains out of equilibrium because  $s_{\lambda_{\max}}(t) \rightarrow$  random walk, diffusive

although all the others have a finite relaxation time.

$\sim O(N)$  model  $\Rightarrow$  field formulation

get ultimately to  $\frac{\partial \tilde{\phi}_a(\vec{k}, t)}{\partial t} = -k^2 \tilde{\phi}_a(\vec{k}, t) + z(t) \tilde{\phi}_a(\vec{k}, t) + \tilde{\xi}_{sa}(\vec{k}, t)$

spin model  
 $\left\{ \begin{array}{l} \phi = s \\ \vec{k} = \mu \\ k^2 = \lambda_{\mu} \end{array} \right.$

$\rightarrow$  all coordinates decouple

$\rightarrow$  all behave like harmonic oscillator, except for  $k=0$ : diffusive mode

$\equiv$  DOMAIN GROWTH

$\sim \ln(t) \sim \ln(\ln(t))$

p=2 n=0 LFC & DEAN 99 CHEER Fyodorov

# FORMALISM I

SYST  
 BATH

## Langevin equations.

↳ Can be derived from scratch by considering a system coupled to the bath + Newton mechanics.

$$H = H_{\text{SYST}} + H_{\text{BATH}} + H_{\text{INT}} (+ H_{\text{COUNTERTERMS}})$$

model BATH → oscillators  $a=1, \dots, N \rightarrow \frac{m_a v_a^2}{2} + \frac{m_a \omega_a^2}{2} q_a^2$   
 model INTERACTIONS → linear couplings  $\sum_{a=1}^N c_a q_a \cdot U(x)$  function of particle position  
 model SYSTEM → one particle  $p, x$

We can solve Newton for oscillators, given some initial conditions  $q_a(0), v_a(0)$ .

$$\begin{cases}
 q_a(t; \text{syst}, q_a(0), v_a(0)) \\
 v_a(t; \text{syst}, q_a(0), v_a(0))
 \end{cases}$$

↳ which yield for our system the following equations of motion:

$$m \ddot{x}(t) + \nu'(\dot{x}(t)) \int_0^t dt' \Gamma(t-t') U'(x'(t')) \dot{x}(t') = F(x(t)) + \nu'(x(t)) \zeta(t)$$

delayed friction
deterministic force

DETERMINISTIC EQUATION!

$$\Rightarrow \int \zeta(t) = \text{function of } \{q_a(0), v_a(0), m_a, \omega_a, c_a\} \\
 \Gamma(t-t') = \text{function of } \{m_a, \omega_a, c_a\}$$

Stochasticity is introduced by assuming  $q_a(0), v_a(0)$  v pdf = e  
 $\Rightarrow \zeta(t)$  gaussian noise:  $\langle \zeta(t) \rangle = 0$   
 $\langle \zeta(t) \zeta(t') \rangle = k_B T \Gamma(t-t')$

$-\beta (H_{\text{BATH}} + H_{\text{INT}})$   
 $\equiv$  assume oscillators all in eq. at temperature  $\beta$  at  $t=0$ .

↳  $\nu'(x(t)) \zeta(t) \equiv$  multiplicative noise term!

↳ The exact same as from the friction  
 Choice of  $\{m_a, \omega_a, c_a\} \rightarrow$  different  $\Gamma(t-t') \rightarrow$  memory kernel

Assume furthermore:

i/ The time scale of the bath  $t_{\text{BATH}} \ll$  all other time scales in the system, so that we have  $\Gamma(t-t') = 2 \delta(t-t') \Rightarrow$  WHITE NOISE CASE  
 $\rightarrow$  although still multiplicative  $p(\omega_a)$  flat.

ii/  $U(x) = x \equiv$  linear coupling  $\Rightarrow$  ADDITIVE NOISE

iii/  $t_F = \frac{m}{\gamma_0} \ll$  time all other scales in system  $\Rightarrow$  OVERDAMPED LIMIT  $\gamma_0 \dot{x} = F(x) + \zeta(t)$

THE MESSAGE HERE: write Langevin carefully to keep the assumption that the bath is in equilibrium and thereby keep the possibility of the system to be in equilibrium.

## Stochastic calculus

Why care about multiplicative noise?  $\rightarrow$  makes the result depend on the rules of calculus for discrete time  
 (Ito vs Stratonovich...)  
 $\rightarrow \frac{d\pi}{dt} \leftrightarrow (1-\alpha)\pi(t_k) + \alpha \pi(t_{k+1})$

↳ equivalence formula  $\ddot{x} \stackrel{\times}{=} f(x(t)) + g(x(t)) \zeta(t)$

$x' \neq dx \oplus f \leftarrow f + \text{diff term} \rightarrow$  same results...

WHY ADDITIVE NOISE DOES NOT HAVE SPATIAL PB?

$$x(t_{k+1}) - x(t_k) = \underbrace{f(\bar{x}(t_k))dt + g(\bar{x}(t_k))\xi(t_k)}_{o(dt) \ll o(dt^{1/2})} dt \quad \langle \xi(t)\xi(t') \rangle \propto \frac{1}{dt} \Rightarrow \xi(t_k) \sim \frac{1}{dt^{1/2}}$$

$\Rightarrow x(t_{k+1}) - x(t_k) \sim o(dt^{1/2})$   
 and  $g(x) - g(\bar{x}) \approx \rightarrow$  not negligible, and so because multiplied by the noise

17/07/2017  
 REF OKSENDAL

$\frac{dx}{dt} = f(x) + g(x)\xi$  the stochastic diff. eq. is properly defined only after the evaluation of the  $x_s$  in the r.h.s explicitly:  $f(\bar{x}(t_k)) g(\bar{x}(t_k))$   
 $\hookrightarrow \bar{x}(t_k) = (1-\alpha)x(t_k) + \alpha x(t_{k+1})$   $\alpha = 1/2$  Stratonovich  
 $\alpha = 0$  Ito

$\rightarrow$  CHAIN RULE as fixed by the value of  $\alpha$  chosen:

$$\frac{dY(x)}{dt} = \frac{dY}{dx} \frac{dx}{dt} + D(1-2\alpha) \frac{d^2Y}{dx^2} g^2(x)$$

$\rightarrow$  usual only if  $\alpha = 1/2$   
 $\Delta$  same to build the solution with  $\alpha = 0$  but beware to add all necessary terms!  
 additional time given by  $\langle \xi(t_k)\xi(t_k) \rangle \propto \frac{D}{dt} \delta t$  comes from the  $\delta(t_k - t_k) \rightarrow \frac{\delta t}{dt}$


$\Delta$  if integrating numerically with  $\neq \alpha \Rightarrow$  different ensemble if  $g$  is not constant (multiplicative noise)  
 PROOF:  $g(\bar{x}_\alpha(t_k))\xi(t_k) - g(\bar{x}_{\alpha'}(t_k))\xi(t_k) = g'(x(t_k))(\alpha - \alpha') dx \xi(t_k) = O(1) \cdot O(dt^{1/2}) \cdot O(dt^{1/2})$

Fokker-Planck equation  $\frac{\partial P}{\partial t} = -\partial_x \left[ (f(x) + 2D\alpha g(x)g'(x)) P(x,t) \right] + D\partial_x^2 [g^2(x) P(x,t)]$

$\hookrightarrow$  Now choosing wisely the force, we can have equivalence between different  $\alpha$ 's.  
 Same process for:  $f + 2D\alpha g g' = f_{eff} + 2D\alpha' g g'$   
 $\hookrightarrow$  to time!

Steady state:  $P_{st}(x) = \frac{1}{Z} e^{-\frac{1}{D} V_{eff}(x)}$  with  $V_{eff}(x) = -\int dx' f(x') + 2D(1-\alpha) \log g(x)$

external potential  $U(x)$ , with  $V_{eff}(x) = U(x)$  if  $f(x) = -g^2(x)U'(x) + 2D(1-\alpha)g(x)g'(x)$

e.g. Brownian motion experiment in small volume  $\rightarrow$  feels the walls  friction  $\gamma(\bar{x}) \rightarrow \langle \xi(t)\xi(t') \rangle = 2\gamma(\bar{x}) \delta(t-t')$  with spatial dependence.  $\hookrightarrow$  MULTIPLICATIVE NOISE

FORMALISM II

Functional formalism (Feynmann path integrals)

- Well suited for:
- perturbative expansion
  - time dependent RG
  - self consistent approximation  $\Rightarrow p > 2$  spin models, glasses
  - dynamical symmetries  $\Rightarrow$  exact results for systems in eq (FDT) out eq FT

$\hookrightarrow$  SLIDES  $\rightarrow$  REVIEW: LFC & Lecomte 1704