

## Lecture 2

- How do granular materials respond to stress? Why are stresses localized? ②

1. How do we think about this question for elastic materials.?

$$\nabla \cdot \sigma = \vec{f}_{\text{ext}}$$

$$\underline{\underline{2D}} \quad \begin{aligned} \partial_y \sigma_{yy} + \partial_x \sigma_{xy} &= f_y \\ \partial_y \sigma_{yx} + \partial_x \sigma_{xx} &= f_x \end{aligned}$$

AND  $\sigma_{xy} = \sigma_{yx}$  (torque balance)

2 eqns for 3 unknowns.

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl}$$

strain tensor

$$\epsilon_{ij} = \frac{1}{2} \left[ \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right]$$

where  $\vec{u}$  is the displacement field measured from a reference state (zero stress)

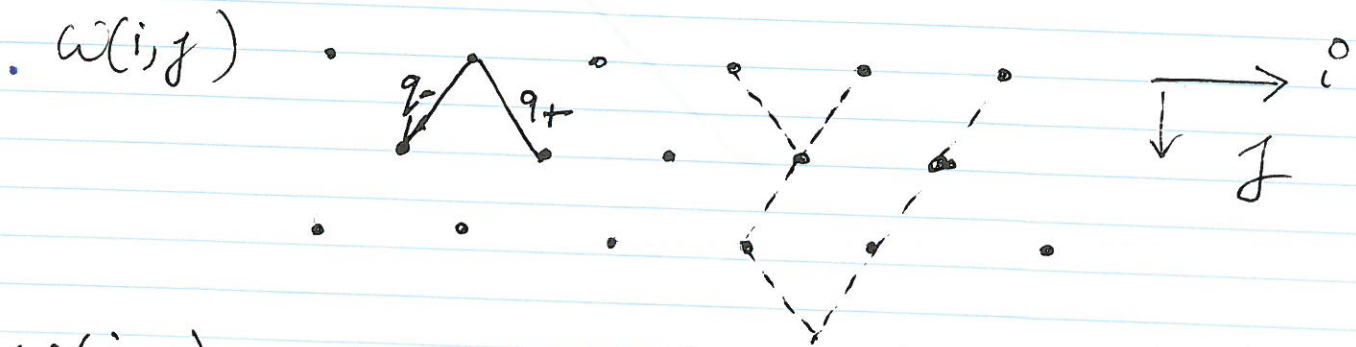
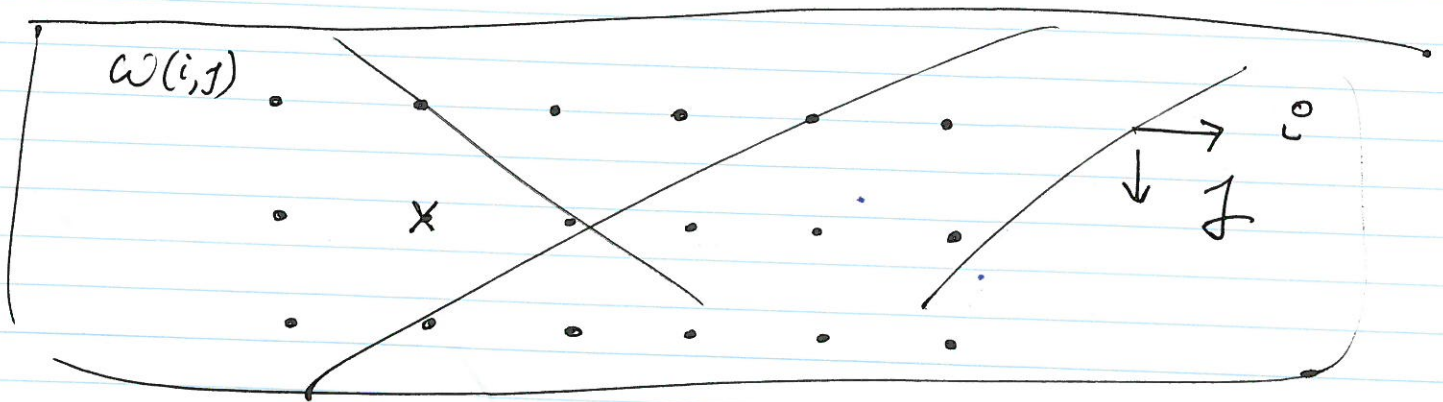
Compatibility Condition

$$\begin{aligned} \partial_y^2 u_{xx} + \partial_x^2 u_{yy} - 2 \partial_x \partial_y u_{xy} &= 0 \\ \left[ \partial_y^4 + 2 \partial_x^2 \partial_y^2 + \partial_x^4 \right] \sigma_{ij} &= 0 \end{aligned}$$

The lack of a reference state  $\Rightarrow$  these closure relations are not available to us.

Stress-only approach

q-model



$$\omega(i, j) = \omega_0 + q_+(i-1, j-1) \omega(i-1, j-1) + q_-(i+1, j-1) \omega(i+1, j-1)$$

Ordered  $q_+ = q_- = \frac{1}{2}$

$$\omega(i, j) = \omega_0 + \frac{1}{2} [\omega(i-1, j-1) + \omega(i+1, j-1)]$$

Master eqn for random walks in space "i" and time "j"



④

$$\frac{dP(n,t)}{dt} = -\sum x_{n,m} P(n,t) + \sum x_{m,n} P(m,t)$$

$q_+$  or  $q_- = 1$  the other is zero.

coalescing random walks

- Impose scalar force balance
- Disorder is coded in the  $q$ 's [contact loading and  $d_{th}$ .
- Uniform distribution of  $q$ 's (sort of an Edwards assumption)

• Advantage  $\Rightarrow$  solve for  $P(\omega)$

for a uniform disbn of  $q$ 's

$$j \rightarrow \infty \quad P(\omega) = \frac{\omega}{\langle \omega^2 \rangle} e^{-\frac{\omega}{\langle \omega \rangle}}$$

Exponential tail [from uniform disbn]

- Exponential tail is robust as long as we don't take the  $q=0,1$  case.

[Bonchard lectures: Liu et al Science, PRE ~ 2002]

(5)

The scalar model  $\rightarrow$  continuum limit.

$$\partial_t \omega = f + D_0 \partial_{xx}^2 \omega \quad \text{if } q_{\pm} = \frac{1}{2}$$

Diffusion.

add disorder  $q_{\pm} = (1 \pm \nu(i,j)) / 2$


small  $\nu$

$$\Rightarrow D_R = D_0 + \text{cor}$$

that depends on size of  $\nu$ .

Response of a point force applied at the top of a pile

• Like diffusion of a  $\delta$ -fn

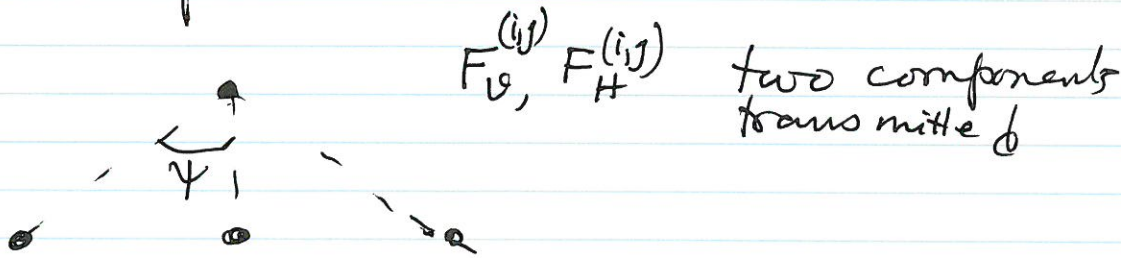
$\rightarrow$  Broadens 

no "chains"

• Missing vectorial force - balance.

(continuing in this vein of thinking)

some simple models



• assume force gets transmitted only at skin of leg (frictionless)



6

2. a fraction  $p$  of  $F_v$  gets lost along middle leg

$F_v$  :  $p$  along middle  
 $(1-p) \frac{(1+\epsilon)}{2}$  along right.  
 $(1-p) \frac{(1-\epsilon)}{2}$  along left.

Balance of horizontal force on  $(i, j)$

requires  $\epsilon = \frac{1}{(1-p) \tan \psi} \frac{F_H(i, j)}{F_V(i, j)}$

$F_H$  was absent in  $q$  mod.

•  $\epsilon \neq 0 \Rightarrow q_+$  and  $q_-$  have to be different

• biases propagation of  $F_V$  along  $F_H$

$$\partial_y F_V + \partial_x F_H = f + a(1-p) \partial_{yy}^2 F_V$$

$$\partial_y F_H + \partial_x [c_0^2 F_V] = \frac{a}{2} \partial_{xx}^2 F_H$$

$$c_0^2 = (1-p) \tan^2 \psi$$

• eliminate  $F_H \Rightarrow \left[ \partial_y^2 - c_0^2 \partial_x^2 \right] F_V = 0$   
Wave equation. !

(7)

• characteristics

$$x - c_0 y, \quad x + c_0 y$$

along which the wave propagates

$\Rightarrow$  force chains as soon as you ~~inc~~ include vector force in.

~~• Any stress component  $\sigma_{xx}$  of the form~~

• connect to

$$\partial_y \sigma_{yy} + \partial_x \sigma_{xy} = f$$

$$\partial_y \sigma_{yx} + \partial_x \sigma_{xx} = 0$$

oif. ignore  $\partial_{xx}^2, \partial_{yy}^2$  in  $F_H, F_V$  eqn.

$$\sigma_{xy} = F_H,$$

$$\sigma_{xx} = c_0^2 \sigma_{yy}$$

• Any closure of 1th form

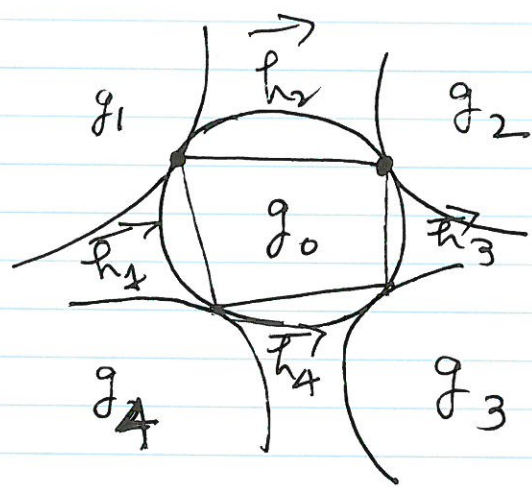
$$\sigma_{xx} = c_0^2 \sigma_{yy} g\left(\frac{\sigma_{xy}^2}{\sigma_{yy}^2}\right)$$

leads to wave-like propagation.

$\rightarrow$  • Breaks rotational symmetry.



We have the tools to do better!



$$\vec{f}_{g_0, g_1}, \vec{f}_{g_0, g_2}, \vec{f}_{g_0, g_3}, \vec{f}_{g_0, g_4}$$

$$\begin{aligned} \vec{f}_{g_0, g_1} &= \vec{h}_1 - \vec{h}_2 + \vec{\Phi}_{g_1} - \vec{\Phi}_{g_0} \\ \vec{f}_{g_0, g_2} &= \vec{h}_2 - \vec{h}_3 + \vec{\Phi}_{g_2} - \vec{\Phi}_{g_0} \\ \vec{f}_{g_0, g_3} &= \vec{h}_3 - \vec{h}_4 + \vec{\Phi}_{g_3} - \vec{\Phi}_{g_0} \\ \vec{f}_{g_0, g_4} &= \vec{h}_4 - \vec{h}_1 + \vec{\Phi}_{g_4} - \vec{\Phi}_{g_0} \end{aligned}$$

Fails if we have body forces such as gravity

$$\sum \vec{f}_{g_0, g_i} = -\vec{f}_{g_0}^{body} \neq 0$$

$$= -\vec{f}_{g_0}^{body} = ( ) + ?$$

- Each contact has two loops and two grains involved. Can we introduce auxiliary fields on the grains?

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$$-\vec{f}_{g_0}^{\text{body}} = \vec{\Phi}_{g_1} + \vec{\Phi}_{g_2} + \vec{\Phi}_{g_3} + \vec{\Phi}_{g_4} - 4\vec{\Phi}_{g_0}$$

This is the discrete Laplacian

$$-\vec{f}_{g_0}^{\text{body}} = \square^2 \vec{\Phi}_{g_0}$$

Reminder 9 model  $\partial_t \omega = \partial_{xx}^2 \omega$

Define a ket  $|\phi\rangle = \{\vec{\Phi}_1 \dots \vec{\Phi}_N\}$

and  $|\vec{f}^{\text{body}}\rangle = \{f_1^{\text{body}} \dots f_N^{\text{body}}\}$  for  $N$ -grain

$$\square^2 |\phi\rangle = -|\vec{f}^{\text{body}}\rangle$$

$$\square^2 = \begin{bmatrix} -\delta_1 & 0 & 1 & \dots & 1 & \dots \\ 0 & -\delta_2 & & & & \dots \end{bmatrix} \quad \begin{matrix} \delta_1 \text{ entries are } = 1 \\ \delta_2 \text{ " " " } = 1 \end{matrix}$$

Graph Laplacian [graph with loops]  
Real-space network captured by  $\square^2$



• Response to  $\omega$   
depends on

• How localized  
then is the  
nature of

$$\square^2$$

•  $\square^2 = \sum_{i=1}^N d_i$

• One zero eigenvalue  
with  $|\lambda_1\rangle =$

• All other  $\lambda$

• Eliminate

$$|\tilde{f}\rangle = |f\rangle$$

• Can invert ~~the~~ after

•  $|\phi\rangle = -$   
 $(\square^2)^{-1} \square^2 =$

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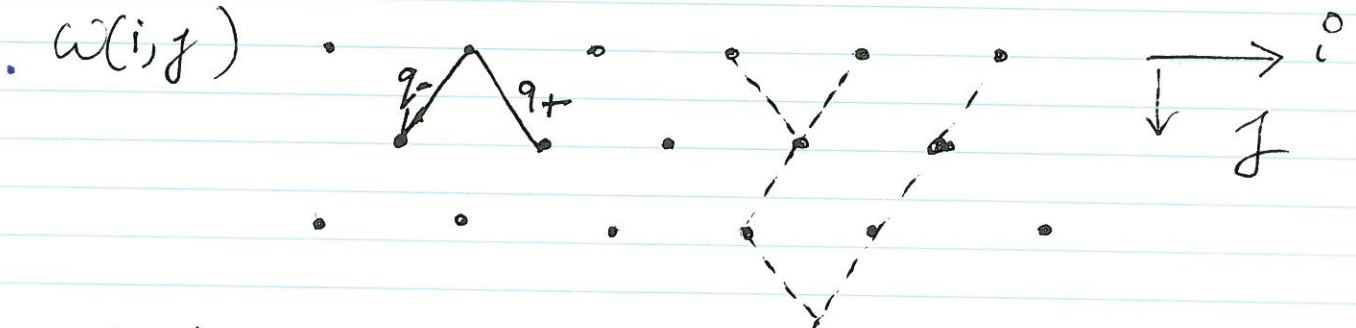
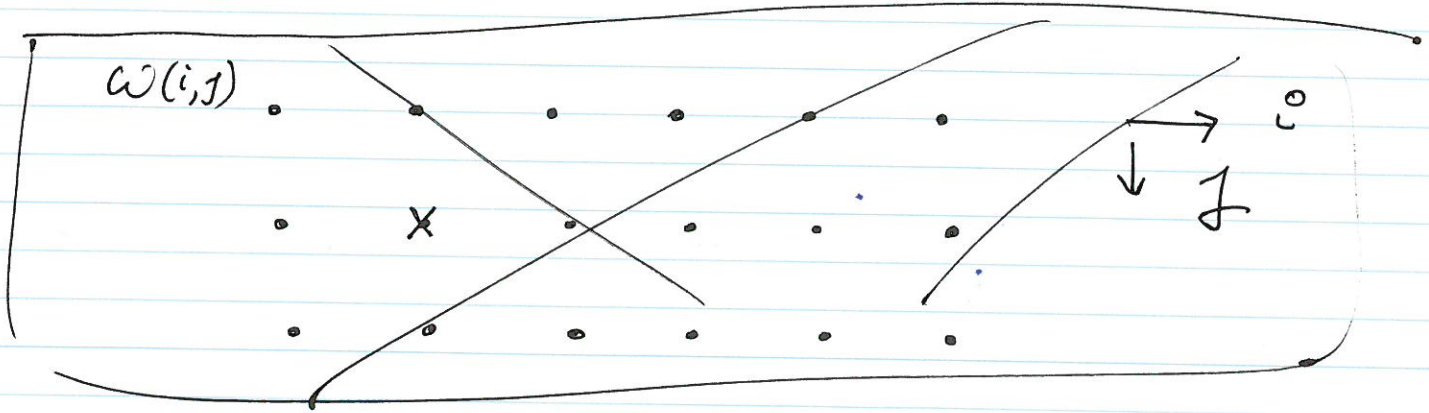
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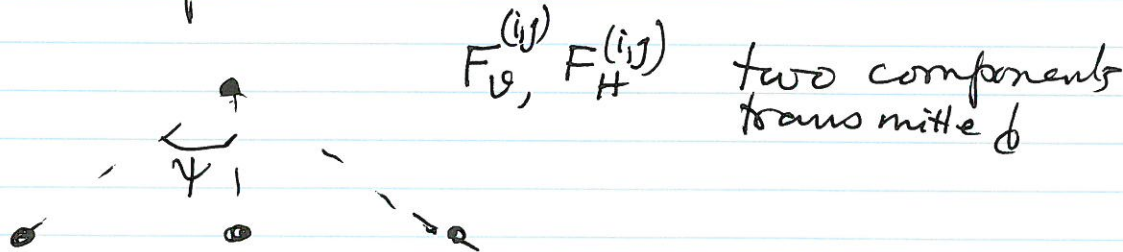
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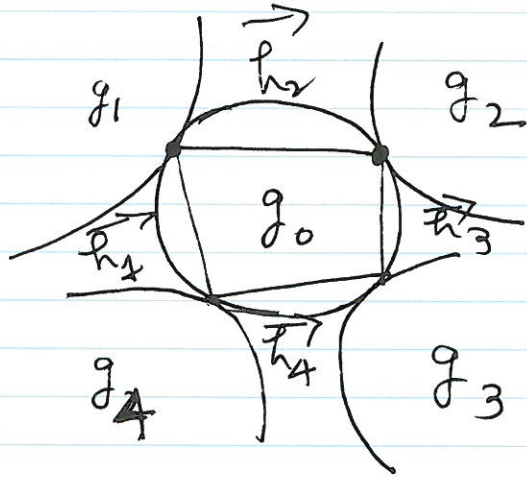
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Graph Laplacian [Graph with loops]

Real-space network captured by  $\square^2$

• Response to a given  $|f^{\text{body}}\rangle$  depends on the spectrum of  $\square^2$

• How localized the response is then is determined by the nature of the eigenfunks of

$$\square^2$$

$$\square^2 = \sum_{i=1}^N \lambda_i |\lambda_i\rangle \langle \lambda_i|$$

• One zero eigenvalue.

$$\text{with } |\lambda_1\rangle = \{1, \dots, 1\} \quad \text{because of row sum} \\ = 0$$

• All other  $\lambda$  are -ve.

• Eliminate  $|\lambda_1\rangle$  by

$$|\tilde{f}\rangle = |f^{\text{body}}\rangle - \frac{1}{N} \sum_{i=1}^N |f^{\text{body}}\rangle$$

• Can invert ~~by~~ <sup>after</sup> project out zero m.

$$|\phi\rangle = -[\square^2]^{-1} |\tilde{f}^{\text{body}}\rangle$$

$$(\square^2)^{-1} \square^2 = 1 - |\lambda_1\rangle \langle \lambda_1|$$



(11)

$$|\Phi\rangle = \sum_{i \neq 1} \frac{1}{\lambda_i} \langle \lambda_i | \tilde{f}^{\text{body}} | \lambda_i \rangle$$

Can construct "new"  $\vec{f}_{g_0, g_1}$

from  $|\Phi\rangle$

NOTE : Whenever I mentioned the "Coulomb Condition" it referred to the constraint  $f_t \leq \mu f_N$  : nothing to do with E&M! Sorry for not explaining this granular terminology. Mohr-Coulomb failure in granular solids is the original model of failure where the condition above is violated.