Back to Vertex Model: Convergent Extension



During convergent extension, tissue doubles in length in 2 hours at fixed area



Sadjad Arzash, Lisa Manning







Myosin Polarization Drives Convergent Extension

Developmental Cell, Vol. 6, 343–355, March, 2004, Copyright @2004 by Cell Press

Patterned Gene Expression Directs Bipolar Planar Polarity in Drosophila

Jennifer A. Zallen* and Eric Wieschaus Department of Molecular Biology Princeton University Lewis Thomas Lab Washington Road Princeton, New Jersey 08544

that eliminate dorsal or ventral cel Wieschaus, 1994). Instead, the patt along the A-P axis, perpendicular to movement, is required for intercala the Even-skipped (Eve) transcription in stripes along the A-P axis, and ge is strongly reduced in embryos whe



Myosin || is highly localized on vertical edges at the onset of convergent extension



Myosin-dependent junction remodelling controls planar cell intercalation and axis elongation

Claire Bertet, Lawrence Sulak & Thomas Lecuit







- Myosin || is highly localized on vertical edges
- The contractility of actomyosin (high tension) shrinks vertical edges
- **Results in these directed cell** rearrangements that are necessary for tissue flow

Introduce Edge Tensions as Parameters

Vertex model with edge tensions





 $E = \sum_{\text{cells}} E_i = \sum_{\text{cells}} \left[K_{A,i} (A_i - A_{0,i})^2 + K_{P,i} (P_i - P_{0,i})^2 \right] + \sum_{\text{edges}} T_{ij} \ell_{ij}$ local rule $\propto \cos 2\theta$ GO TO SLIDES

Convergent Extension Driven by Edge Tensions





Convergent Extension Driven by Edge Tensions



Convergent Extension Driven by Edge Tensions

Convergent Extension Accompanied by T1 events

TI Events Are Oriented

TI Events Are Oriented

Tension on Vanishing Edge Increases Before T1 event

They all show an increasing trend of tension before undergoing T1

1.4

1.3

Normalized Tension 0.9

0.7

Similar to Active TIs

Brauns ++ bioRXiv (2023)

	S

Compare to Applying Global Shear to Vertex Model

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Tension on Vanishing Edges Remains Flat Before T1

Different Mean Shape Factors During Active vs. Passive Extension

Double Optimization: Is Many More Different?

- Cost function: $\mathcal{C} = (\Delta - \Delta p_T)^2$
- Parameters: edge conductances
- Physical cost function: dissipated power
- Physical DOF: node pressures or edge currents
- Ist optimzn: Minimize power wrt physical DOF —required by physics!
- 2nd optimzn: Use gradient descent to minimize control cost function wrt control DOF

Is many more different? Tune for N_T targets with response Δ

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Rocks, Ronellenfitsch, Liu, Nagel, Katifori PNAS 2019

Yes: Many More is Different

• System can satisfy more targets as system size increases

Rocks, Ronellenfitsch, Liu, Nagel, Katifori PNAS 2019

Many More is Indeed Different

- satisfaction transition)
- But here we have 2 sets of DOF—parameters + physical DOF
- Does that change anything?

• But many more is different in a familiar way—a phase transition (constraint-

Yes it can: Funnel Landscape Inspired by Protein Folding

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Instead of minimizing

minimize

$$\hat{F} = \sum_{i=1}^{N_T} \frac{1}{R_i^{2\beta}} (\Delta - \Delta V_i)^2 \Theta (\Delta - \Delta V_i)$$

 R_i is distance from target *i* to source • This provides funnel in space to tune targets in order of distance from source

M Ruiz Garcia, AJ Liu, E Katifori PRE (2019)

Changing Cost Function Changes N-Dependence!

Steepness of funnel controls scaling

- For large β , N^{T^c} ~ N and width/N is constant as N $\rightarrow \infty$ (same as Hopfield)
- SAT/UNSAT transition is not sharp

How many more is different is subtle and needs to be understood

- Simultaneous optimization of cost function and physical Lypunov function provides systematic \bullet way of solving inverse design problems: very general
- Biological systems with adaptive function use local rules to adjust parameters
 - What are the parameters?
 - What is the process by which they are adjusted??
- Unusual kind of condensed matter
 - Many more is different because more constraints can be satisfied with more parameters But nature of constraint-satisfaction transition depends on cost function and we don't know
 - what it is in biological contexts
- Important for understanding function in living matter
 - Speculation: biology stays in overparameterized regime \bullet
 - Easiest to introduce extensive number of parameters
 - Easy to get good solutions in overparameterized regime
 - Good solutions are more generalizable with many flat directions & representational drift

Summary

Learning about Learning Metamaterials

Felipe Rodrigues Martins Marcelo Guzman Nachi Stern Jason Rocks Vijay Balasubramanian Eleni Katifori

UPenn UPenn UPenn **UPenn/BU** UPenn UPenn

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- Andrea J. Liu
- University of Pennsylvania

Menachem Stern

Marcelo Guzman

Felipe

Martins

Jason Rocks

Eleni Katifori

Vijay Balasubramanian

DOE Biomolecular Materials **NSF DMR Materials** Theory **NSF UPenn NRT Simons Foundation**

How do input/output responses emerge as collective phenomena?

- Goal of stat phys: to gain microscopic understanding of macroscopic (collective) phenomena in many-body systems
- This requires
 - Reducing microstate information (e.g. positions and velocities) to averages/variances (distributions) of relevant microscopic quantities (eg order parameters)
- For over a century, statistical physics has provided
 - solution to dimensional reduction problem
 - bridge between micro & macro scales via relevant micro variables
- But some problems resist statistical physics
 - Far from equilibrium
 - Complex landscape
 - Correlated disorder

Input/Output Problems are Resistant to Statistical Physics

- For protein allostery
 - there are 20 different amino acids at each site (adaptive DOF)
 amino acid sequence (values of adaptive DOF) not chosen randomly
 - amino acid sequence (values of adaptive but by evolution/natural selection
- For flow allostery
 - there are 10⁶ edges in brain vasculature with range of potential conductances for each
 - vasculature does not choose conductances (adaptive DOF) randomly but to satisfy input/output relations
- We need new approaches for these hard problems

Input/Output Problems Require Ensembles

- "Stat Phys" requires ensembles
 - Here we need big designed/evolved ensembles
- We have protein families across species
- But these are small by stat mech standards
- New material design approach allows us to construct large ensembles! "statistical physics"
 - Consequence of overparameterization

Goodrich PRL 2015 Rocks PNAS 2017 Hexner Soft Matter 2018 Hexner PRE 2018 Rocks PNAS 2019 Pashine Sci Advances 2019 Pashine Hexner PRR 2020 Hexner PNAS 2020 Rocks PRL 2021 Rocks PRR 2020

- We now have designed ensembles
- So what do we want to know??
- of function at macroscopic scale?
- What happens to networks when they learn function?

• Where to start?

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• How does edge tuning at microscopic scale lead to emergent collective phenomenon

Where to Start in Learning about Learning?

- When in doubt, look at simplest case in extreme limits
- Consider I source edge with $\Delta V = I$ and one target edge with $\Delta V = \Delta = I$
- System partitions into two regions of constant voltage separated by lowconductance barrier

Function Requires Simultaneous Minimization in Two Landscapes

- Both landscapes evolve during learning
 - Cost function depends on physical DOF (assumed equilibrated)
 - Power depends on adaptive DOF
 - Cost Hessian tells us curvatures in phase space of adaptive DOF

$$H_L = \frac{\partial^2 \mathcal{L}}{\partial k_i \partial k_j}$$

- phase space of adaptive DOF
- This is much studied in stat phys of ML

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• Eigenvalues of H_L are curvatures, eigenvectors are corresponding directions in

Cost Hessian Evolves During Learning

- Cost Hessian develops a gap at high end due to learning
- Highest eigenvalue reflects what was learned

Learning Hessian Eigenvalues

Cost Hessian Evolves During Learning

- Cost Hessian develops a gap at high end due to learning
- Highest eigenvalue reflects what was learned

Highest Eigenvectors of Cost Hessian Capture Response

- In this extreme case, system divides into 2 sectors separated by lowconductance barrier
- Useful to verify we have captured the right physics
- But not what we want because it requires knowing learning cost function

-1.00

How to Capture Response Without Learning Cost Function?

- For $\Delta = I$, system partitions into two regions of constant voltage
- But what if $\Delta < I$?
- In extreme limit $\Delta = I$, edge-tuning/function relation is topological
- Use persistent homology to identify features responsible for function

- Increase voltage drop and add edge a edge
- Register appearance of new basin as "birth" of basin
- Connected components (0 Betti number)

Increase voltage drop and add edge as you reach the voltage drop across the

"birth" of basir nber)

- edge
- Register appearance of new basin as "birth" of basin

Increase voltage drop and add edge as you reach the voltage drop across the

- edge
- Register appearance of new basin as "birth" of basin

• Increase voltage drop and add edge as you reach the voltage drop across the

younger basin

Register merging of two basins into one when saddle is reached as "death" of

younger basin

• Register merging of two basins into one when saddle is reached as "death" of

Persistent Homology Approach

- For each feature, plot death value of ΔV vs. birth value
- Small shallow basins in landscape fall near diagonal
- "Persistent" features lie far from diagonal

ΔV vs. birth value near diagonal gonal

Effect of Tuning on Ensemble Heat Map Persistence Diagram

- persist all the way up to Δ
- \bullet regions of approx uniform node voltage)

Descending: tuned networks have many inverted basins with $\Delta V_b = \Delta$ ("cracks" that separate

Effect of Tuning on Persistence Diagram

- Look at extreme case where $\Delta = I$
- Ascending: tuned networks have many basins with $\Delta p_b=0$ (uniform node pressures) that persist all the way up to Δ
- Descending: tuned networks have many inverted basins with $\Delta p_b = \Delta$ ("cracks" of removed edges that separate regions of uniform pressure)

These Features Really Do Correlate with Δ

Voltage Difference Landscape

Step 0: Look at Voltage Difference Landscape

Persistence (Significance) Simplify in order of increasing τ (barrier height)

Persistence (Significance) Simplify in order of increasing τ (barrier height)

Persistence (Significance) Simplify in order of increasing τ (barrier height) Rocks, Liu, Katifori PRL 2021 Stop just before target nodes join same basin Rocks, Liu, Katifori PRR 2020

Persistent Homology Captures Function Quantitatively

• Yes, it works!

tuned voltage drop

Electrical Networks vs Mechanical Networks

- In flow networks, sectors of nearly uniform node pressure or pathways of edges with nearly uniformly high pressure drops yield same information
- In mechanical networks, focus on local strain instead of pressure
- Unlike pressure, strain is defined over region not individual edges
- sectors of nearly uniform strain/pathways of nearly uniformly high strain do not yield same information

LRMSD Replaces Pressure/Voltage Difference

- Local root-mean-squared displacements measures deviation of node displacements in neighborhood with respect to rigid translations/rotations
 First define local deformation tensor \$\har{F}\$ around node i that best describes around node i that best describes are the section in the section is the section is the section in the section is the section in the section is the section is the section is the section is the section in the section is the
- First define local deformation tensor F around node it is normalized in the set of $\hat{F} = \left[\sum_{j} w_{ij} \left(\vec{b}_{ij} + \Delta \vec{u}_{ij}\right) \vec{b}_{ij}^{T}\right] \left[\sum_{k} w_{ik} \Delta \vec{b}_{ik} \vec{b}_{ik}^{T}\right]^{-1}$
- Weights w_{ij} favor nodes j that are close to node i $w_{ij} = -$
- \hat{b}_{ij} is vector from node i to node j without source strain
- $\Delta \vec{u}_{ij}$ is displacement of node i from node j due to source strain
- $R = \hat{F}(\hat{F}^T\hat{F})^{-1/2}$ ~ local rigid-body rotation matrix

 $\delta u_i =$

• LRMSD for node i

$$\frac{e^{-\frac{\sigma_{ij}}{2\sigma^2}}\Theta(\ell_{\max}-\ell_{ij})(1-\frac{\ell_{ik}^2}{2\sigma^2})}{\sum e^{-\frac{\ell_{ik}^2}{2\sigma^2}}\Theta(\ell_{\max}-\ell_{ik})(1-\frac{\ell_{ik}}{2\sigma^2})}$$

$$w_{ij} \left[\Delta \vec{u}_{ij} - (R - I) \vec{b}_{ij} \right]^2$$

 $-\delta_{ik})$

Hinge pathway connects minimum δu within each sector with pathway of lowest $\delta \hat{u}$

> δu_h is max δu along pathway

 δu^* is max δu at source/target nodes

 $\delta u_h / \delta u^*$ quantifies significance of hinge sectors

Hinge and Pathway Scales

Strain pathway is pathway of highest δu connecting source to target

 δu_{sp} is min δu along pathway

 δu^* is max δu at source/target nodes

 $\delta u_{sp}/\delta u^*$ quantifies significance of strain pathway

Persistent Homology for Mechanical Networks

- Classify with strain pathway scale and hinge scale
- Continuum of mechanisms from hinges to strain pathways
- Perhaps this is why allostery mechanisms have resisted easy classification?!

Persistent Homology for Proteins

Persistent Homology Works Reasonably Well for Protein Allostery

- Hinge motion overlap quantifies overlap between predicted and observed
- For sufficiently persistent features, overlap is high
- Drops at very high hinge scale due to fluid/nearly-fluid sectors with large displacements unrelated to allostery

- We now have designed ensembles
- So what do we want to know??
- How does edge tuning at microscopic scale lead to emergent collective phenomenon of allosteric function at macroscopic scale?
- What happens to networks when they learn allostery?
- Edge tuning affects topological structure of response
- Most topologically significant features (sectors/hinges/strain pathways) are responsible for function

- Summary of our approach:
 - Design ensembles of networks with same function
 - Identify microscopic origin of function with topological data analysis
 - Dimensional reduction: allosteric mechanism reduced to 1(2) variables for electrical/ flow (mech) networks
 - Apply analysis to real systems
- What did we learn?
 - Allosteric mechanisms in proteins are not distinct—there is a continuum Mechanism can be specified by two variables that can be extracted from structural
 - measurements

Persistent Homology Works! But Let's Get Even More Ambitious

- We have to apply the inputs in order to carry out PH analysis
- Is it possible to figure out what network has learned without applying inputs? Can we extract the structure-function relation?
- Recall double optimization
 - Cost landscape
 - Cost function: (desired input/output relation free input/output relation)²
 - DOF: edge conductances
 - Cost Hessian (2nd derivative of cost function wrt to parameters): need cost function (inputs)
 - Physical landscape
 - power dissipation
 - physical DOF: node pressures/voltages
 - Physical Hessian: doesn't depend on cost function!

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 - Physical Hessian: doesn't depend on cost function!

What can we learn from the physical Hessian?

Recall Learning Requires Simultaneous Minimization in Two Landscapes

- Power landscape evolves during learning - Power depends on parameters (edge conductances)
- Learning Hessian tells us curvatures in learning phase space

$$H_L = \frac{\partial^2 \mathcal{L}}{\partial k_i \partial k_j}$$

- Eigenvalues of H_L are curvatures, eigenvectors are corresponding directions in learning phase space
- Physical Hessian tells us curvatures in physical phase space

$$H_P = \frac{\partial^2 \mathcal{P}}{\partial V_\alpha \partial V_\beta}$$

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Physical Landscape Flattens in Direction of Learned Response

- Stern, Liu, Balasubramanian, PRE (2024) As system learns
 - Lowest eigenvalues decrease
 - Lowest eigenvectors overlap more with response to inputs
- Lowest eigenvectors tell us about learned response
- Look at lowest eigenvectors of physical Hessian

Evolution of Eigenvalues in Learning and Physical Hessians

Evolution of Eigenvalues in Learning and Physical Hessians

Highest eigenvalues increase

Stern, Guzman, Martins, Liu, Balasubramanian arXiv (2024)

Lowest Mode of Physical Hessian Corresponds to Highest Mode of Cost Hessian

from physical Hessian

from learning Hessian

I source edge: $\Delta V = IV$ I target edge: $\Delta V = IV$

overlap

Felipe Martins, Marcelo Guzman

