### Mechanical Transitions in Cells and Tissues: Day 2

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Boulder School 2001: Nonequilibrium Statistical Physics: Glasses, transport & friction, biological systems, and turbulence

July 2-27, 2001

#### Scientific Coordinators:

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Trajectory





UCLA

Harvard University

Boulder School 2024: Self-Organizing Matter: From Inanimate to the Animate

July 1-26, 2024 Scientific Coordinators

Shiladitya Banerjee (Carnegie Mellon) Andela Saric (IST Austria) Eric R. Dufresne (Cornell) Margaret L. Gardel (Chicago)





Recap: Rigidity Percolation in Spring Networks: Maxwell, Philos. Mag., 1864

Consider a lattice of N nodes in d dimensions, z coordination number, and bond occupation probability p

# of degrees of freedom =Nd

# constraints = 
$$\frac{N}{2} z p$$

Maxwell criterion: Balance # constraints and # degrees of freedom

$$p_c = 2d/z, \quad z_c = 2d$$

Isostatic coordination

 $p > p_c, z > z_c$  Condition for rigidity



## Recap: EMT for central force (spring) networks

Feng, Thorpe, Garboczi, PRB 1985



## Recap: EMT for central force (spring) networks



Extra displacement due to replaced bond

$$\delta_u = \frac{f}{\frac{\alpha_m}{\alpha^*} - \alpha_m + \alpha}$$

$$f = \delta_{um}(\alpha_m - \alpha)$$

$$\delta_{u} = \frac{\delta_{um}(\alpha_{m} - \alpha)}{\frac{\alpha_{m}}{\alpha^{*}} - \alpha_{m} + \alpha}$$

## Recap: EMT for central force (spring) networks

Replace bonds with spring constant  $\alpha_m$  by  $\alpha$  (probability p) and by 0 (probability (1-p)).

When averaged over the entire system, the fluctuations  $\delta_u$  should go to 0.

$$\int \frac{\alpha_m - \alpha'}{\frac{\alpha_m}{a^*} - \alpha_m + \alpha'} * P(\alpha') \, d\alpha' = 0$$

Where 
$$P(\alpha') = p\delta(\alpha' - \alpha) + (1 - p)\delta(\alpha')$$

$$\frac{\alpha_m}{\alpha} = \frac{p - a^*}{1 - a^*}$$

## Recap: EMT for central force (spring) networks What is $a^*$ ?

- Geometric constant relating geometry of lattice to rigidity
- Evaluated in terms of Dynamical Matrix

$$a^* = \frac{1}{3} \sum_{q} Tr \left[ \boldsymbol{D} \ (q) \cdot \boldsymbol{D}^{-1}(q) \right]$$

### **Dynamical Matrix**

Expand the total energy about structural equilibrium coordinates

$$E = E_0 + \frac{\partial E}{\partial u} \cdot u + \frac{1}{2!} \frac{\partial^2 E}{\partial u^2} \cdot u^2 + \frac{1}{3!} \frac{\partial^3 E}{\partial u^3} u^3 + \dots$$

At equilibrium the O(1) term is 0.

$$E = E_0 + \frac{1}{2} \sum \boldsymbol{u}_{\alpha,\kappa,a} \boldsymbol{\Phi}_{\alpha,\alpha'}^{\kappa,\kappa'} \boldsymbol{u}_{\kappa',\alpha',a} + \dots$$

where  $\boldsymbol{u}_{\alpha,\kappa,a}$  is the displacement of atom  $\kappa$  in unit cell *a* in Cartesian direction  $\alpha$ 

## **Dynamical Matrix**

Expand the total energy about structural equilibrium coordinates

$$E = E_0 + \frac{\partial E}{\partial u} \cdot u + \frac{1}{2!} \frac{\partial^2 E}{\partial u^2} \cdot u^2 + \frac{1}{3!} \frac{\partial^3 E}{\partial u^3} u^3 + \dots$$

At equilibrium the O(1) term is 0.

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$$E = E_0 + \frac{1}{2} \sum \boldsymbol{u}_{\alpha,\kappa,a} \boldsymbol{\Phi}_{\alpha,\alpha'}^{\kappa,\kappa'} \boldsymbol{u}_{\kappa',\alpha',a} + \dots$$

In the Harmonic Approximation O(3) and higher order terms are negligible

**Dynamical Matrix** 

$$E = E_0 + \frac{1}{2} \sum \boldsymbol{u}_{\alpha,\kappa,a} \boldsymbol{\Phi}_{\alpha,\alpha'}^{\kappa,\kappa'} \boldsymbol{u}_{\kappa',\alpha',a}$$

The matrix of force constants

$$\Phi_{\alpha,\alpha'}^{\kappa,\kappa'}(a) = \frac{\partial^2 E}{\partial \boldsymbol{u}_{\alpha,\kappa} \partial \boldsymbol{u}_{\kappa',\alpha'}}$$
$$= -\frac{\partial F_{\boldsymbol{u}_{\alpha,\kappa,a}}}{\partial \boldsymbol{u}_{\kappa',\alpha',a}}$$

The dynamical matrix is the Fourier transform of this force constant matrix

**Dynamical Matrix** 

$$E = E_0 + \frac{1}{2} \sum \boldsymbol{u}_{\alpha,\kappa,a} \boldsymbol{\Phi}_{\alpha,\alpha'}^{\kappa,\kappa'} \boldsymbol{u}_{\kappa',\alpha',a}$$

The matrix of *force constants* 

$$\Phi_{\alpha,\alpha'}^{\kappa,\kappa'}(a) = \frac{\partial^2 E}{\partial u_{\alpha,\kappa} \partial u_{\kappa',\alpha'}}$$
$$= -\frac{\partial F_{u_{\alpha,\kappa,a}}}{\partial u_{\kappa',\alpha',a}}$$

The dynamical matrix is the Fourier transform of this force constant matrix

To obtain vibrational modes, solve

$$D^{\kappa,\kappa'}_{\alpha,\alpha'}(\boldsymbol{q})\varepsilon_{m\alpha,\kappa\boldsymbol{q}}=\omega^2_{m,\boldsymbol{q}}\varepsilon_{m\alpha,\kappa\boldsymbol{q}}$$

where 
$$\boldsymbol{u}_{\alpha,\kappa} = \boldsymbol{\varepsilon}_{m\alpha,\kappa} \boldsymbol{q} \boldsymbol{e}^{i\boldsymbol{q}\cdot\boldsymbol{R}_{\alpha,\kappa}-\omega t}$$
 10

## **Dynamical Matrix for a Triangular Lattice**



# For a spring network on a triangular lattice

$$a^* = \frac{1}{3} \sum_{q} Tr \left[ \boldsymbol{D}_s(q) \cdot \boldsymbol{D}^{-1}(q) \right] = \frac{2}{3}$$
$$\frac{\alpha_m}{\alpha} = \begin{cases} \frac{p-a^*}{1-a^*} & \text{if } p > a^* \\ 0 & \text{if } p \le a^* \end{cases}$$

$$p_c = \frac{2}{3}$$
 is our rigidity percolation threshold!

## Phase Transition in Tissue Mechanics during Morphogenesis



Petridou, Corominas-Murtra, Heisenberg, Hannezo Cell 2021

### An Example of Anisotropic Spring Network



# of degrees of freedom =Nd

# of constraints = (1/2) ( $z_x N p_x + z_y N p_y$ )

See: T. Zhang, J.M. Schwarz, MD, PRE 2014

### An Example of Anisotropic Spring Network



# of degrees of freedom =Nd

# of constraints = (1/2) ( $z_x N p_x + z_y N p_y$ )

d=2, 
$$z_x = 2$$
,  $z_y = 4$ 

$$\frac{p_x}{2} + p_y = 1$$

Check EMT gives you the same relationship See: T. Zhang, J.M. Schwarz, MD, PRE 2014

### **Rigidity Percolation in Semiflexible Networks**



#### Study using effective medium theory or energy minimization

### Rigidity Percolation in Semiflexible Networks



Distribution of stretching and bending constants

• 
$$P(\alpha') = p\delta(\alpha' - \alpha) + (1 - p)\delta(\alpha')$$

• 
$$P(\kappa') = p^2 \delta(\kappa' - \kappa) + (1 - p^2) \delta(\kappa')$$

### Rigidity Percolation in a semiflexible networks on triangular lattice: Dynamical Matrix

$$\boldsymbol{D}_{s}(q) = \alpha_{m} \sum_{\langle ij \rangle} \left[ 1 - e^{-i\boldsymbol{q}_{\cdot} \boldsymbol{\hat{r}}_{ij}} \right] \boldsymbol{\hat{r}}_{ij} \boldsymbol{\hat{r}}_{ij}$$

$$\boldsymbol{D}_{b}(q) = \kappa_{m} R^{-2} \sum_{\langle ij \rangle} \left[ 4 (1 - \cos(\boldsymbol{q} \cdot \boldsymbol{\hat{r}}_{ij})) - (1 - \cos(2\boldsymbol{q} \cdot \boldsymbol{\hat{r}}_{ij})) \right] (\boldsymbol{I} - \boldsymbol{\hat{r}}_{ij} \boldsymbol{\hat{r}}_{ij})$$

 $\boldsymbol{D}(q) = \boldsymbol{D}_s(q) + \boldsymbol{D}_b(q)$ 

Rigidity Percolation in a semiflexible networks on triangular lattice: Effective Medium stretching and bending constants from EMT

$$\frac{\alpha_m}{\alpha} = \begin{cases} \frac{p-a^*}{1-a^*} & \text{if } p > a^* \\ 0 & \text{if } p \le a^* \end{cases} \qquad a^* = \frac{1}{3} \sum_q Tr\left[\boldsymbol{D}_s(q) \cdot \boldsymbol{D}^{-1}(q)\right] \\ \frac{\kappa_m}{\kappa} = \begin{cases} \frac{p^2-b^*}{1-b^*} & \text{if } p > \sqrt{b^*}, \\ 0 & \text{if } p \le \sqrt{b^*} \end{cases} \qquad b^* = \frac{1}{3} \sum_q Tr\left[\boldsymbol{D}_b(q)\boldsymbol{D}^{-1}(q)\right] \end{cases}$$

Solve self-consistently

Rigidity Percolation in a semiflexible networks on triangular lattice: Effective Medium stretching and bending constants from EMT

$$\frac{\alpha_m}{\alpha} = \begin{cases} \frac{p-a^*}{1-a^*} & \text{if } p > a^* \\ 0 & \text{if } p \le a^* \end{cases} \qquad a^* = \frac{1}{3} \sum_q Tr\left[\boldsymbol{D}_s(q) \cdot \boldsymbol{D}^{-1}(q)\right] \\ \frac{\kappa_m}{\kappa} = \begin{cases} \frac{p^2-b^*}{1-b^*} & \text{if } p > \sqrt{b^*}, \\ 0 & \text{if } p \le \sqrt{b^*} \end{cases} \qquad b^* = \frac{1}{3} \sum_q Tr\left[\boldsymbol{D}_b(q)\boldsymbol{D}^{-1}(q)\right] \end{cases}$$

Also note:  $a^* + b^* = \frac{2}{3}$ At the rigidity percolation threshold,  $p_c$ :  $p_c + p_c^2 = \frac{2}{3}$ .  $\therefore p_c \approx 0.457$ 

Rigidity Percolation in flexible and semiflexible networks on triangular lattice: EMT prediction of shear modulus G (G =  $(\sqrt{3}/4) \alpha_m$ )



## Rigidity Percolation in semiflexible networks: what happens when we have angle constraining crosslinks between crossing filaments?



Tseng, Wirtz 2001.



Figure 16–42. Molecular Biology of the Cell, 4th Edition.



Svitkina and Borisy 1999.

## Rigidity Percolation in semiflexible networks: what happens when we have angle constraining crosslinks between crossing filaments?

![](_page_22_Figure_1.jpeg)

![](_page_22_Figure_2.jpeg)

![](_page_22_Figure_3.jpeg)

Tseng, Wirtz 2001.

Figure 16–42. Molecular Biology of the Cell, 4th Edition.

Svitkina and Borisy 1999.

![](_page_22_Figure_7.jpeg)

Rigidity Percolation in semiflexible networks: what happens when the network has spatial inhomogeneity?

![](_page_23_Picture_1.jpeg)

Chang, et al., J. Biomed. Res., 2001

### Model: Kagome-lattice based network with structural correlation

•Include randomly chosen bond with acceptance probability  $P = (1 - c)^{6-nn}$ 

- •*c* sets the strength of correlation
- •Larger values of correlation strength yield patchier structures

![](_page_24_Figure_4.jpeg)

### Increasing correlation yields dense clusters

Increasing

correlation

Increasing fraction of occupied bonds

![](_page_25_Picture_9.jpeg)

### Threshold for Rigidity Depends varies Nonmonotonically with Correlation

![](_page_26_Figure_1.jpeg)

## Threshold for Rigidity Depends varies Non-monotonically with Correlation

![](_page_27_Figure_1.jpeg)

### Computing percolation thresholds

 Fit shear modulus around percolation threshold to power law

• 
$$G = k(p - p_c)^{\beta}$$

- $p_c$  denotes the percolation thresholds (depends on c)
- β is a critical exponent found by fitting

![](_page_28_Figure_5.jpeg)

### $p_c$ exhibits reentrance

![](_page_29_Figure_1.jpeg)

# Scaling Exponents Decreases Linearly with Rigidity Threshold

![](_page_30_Figure_1.jpeg)