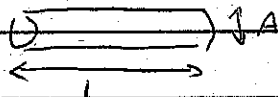


Questions from last time:

1. Efficiency of fish swimming

- Data from Fish + Lauder

- Data I have: $\frac{\text{Energy}}{\text{mass} \cdot \text{dist.}}$

Cylindrical fish:  $m \sim \rho AL$

Sardines: $L \sim 200 \text{ mm}$

$m \sim 100 \text{ g}$

$V \sim 400 \text{ mm/s}$

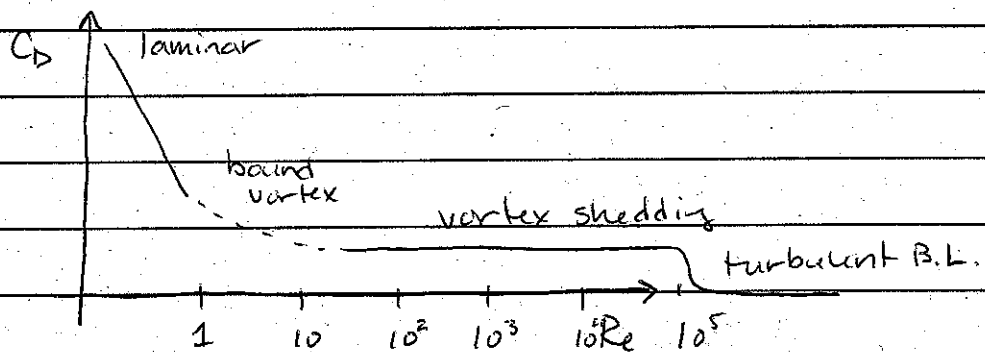
$E \sim 1 \text{ J/kg} \cdot \text{m}$

$$\eta = \frac{F \cdot v}{\phi} = \frac{\frac{1}{2} C_D \rho V^2 A \cdot v}{E m v} = \frac{\frac{1}{2} C_D \rho V^2 A \checkmark}{E \rho A L v} \approx 1$$

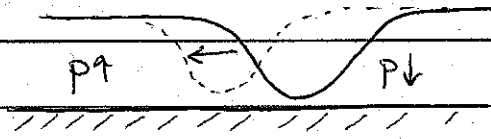
$$= \frac{V^2}{2EL}$$

$\eta_{\text{sardines}} \approx 40\%$

2. Transition from laminar to turbulent drag

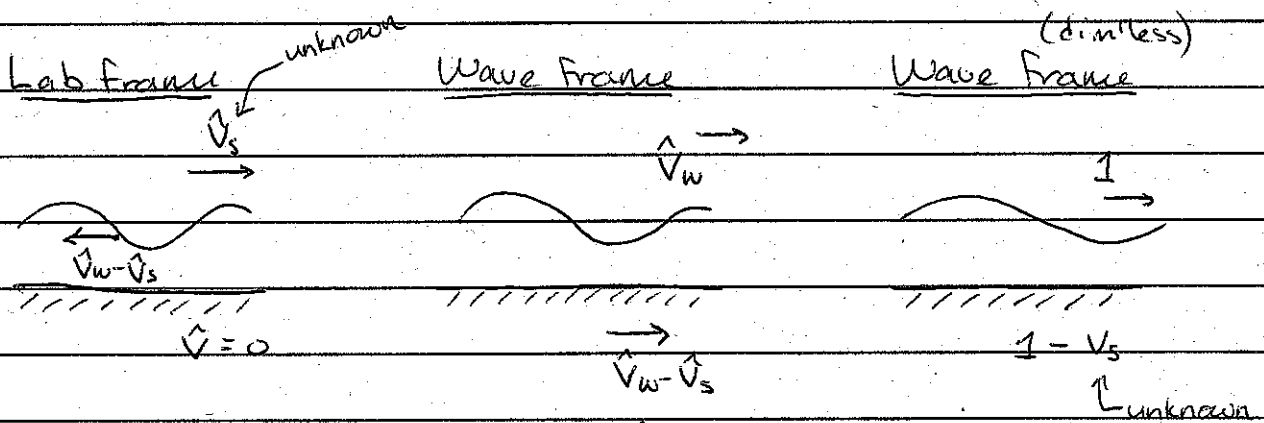


Suppose h is a traveling wave
 $\Rightarrow V_{\text{snail}}$



Find V_s (snail velocity):

- Pick shape of foot $h(x,t)$ (selected by snail)
- Work in frame moving w wave to eliminate time dep.
- "hat" = dimensional quantity



Rescale: $\hat{u} = u \hat{V}_w$, $\hat{v} = v \frac{\hat{H}}{\hat{L}} \hat{V}_w$, $\hat{y} = y \hat{H}$, $\hat{x} = x \hat{L}$
 $\hat{p} = p \frac{\mu \hat{V}_w \hat{L}}{\hat{H}^2}$

Dimless lubrication equation:

$$\frac{\partial \hat{p}}{\partial \hat{x}} = \frac{\partial^2 \hat{u}}{\partial \hat{y}^2}, \quad \frac{\partial \hat{p}}{\partial \hat{y}} = 0$$

$$\Rightarrow \hat{u} = \frac{\partial \hat{p}}{\partial \hat{x}} \frac{1}{2} \hat{y} (\hat{y} - \hat{h}) + V_s \left(\frac{\hat{y}}{\hat{h}} - 1 \right) + 1 \quad \text{(x) cons of mom.}$$

st. st. \Rightarrow Flux = $Q = \int_0^h u dy = \text{const}$

$$Q = -\frac{1}{12} \frac{\partial p}{\partial x} h^3 - \frac{1}{2} h V_s + h \Rightarrow \boxed{\frac{\partial p}{\partial x} = \frac{12}{h^3} \left[h \left(1 - \frac{V_s}{2}\right) - Q \right]}$$

(**) cons of mass

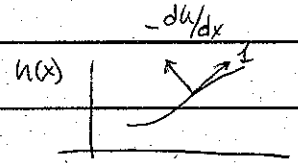
Periodicity $\Rightarrow p(0) = p(1)$

$$\Rightarrow \int_0^1 \frac{\partial p}{\partial x} dx = 0 = \int_0^1 \frac{12}{h^3} \left[h \left(1 - \frac{V_s}{2}\right) - Q \right] dx$$

$$= \left(1 - \frac{V_s}{2}\right) \underbrace{\int_0^1 \frac{dx}{h^2}}_{I_2} - Q \underbrace{\int_0^1 \frac{dx}{h^3}}_{I_3}$$

$$\Rightarrow \boxed{Q = \left(1 - \frac{V_s}{2}\right) \frac{I_2}{I_3}}$$

Force balance: $F = 0$



traction = $f = \underline{\sigma} \cdot \underline{n} \Rightarrow f_x = p \frac{dh}{dx} + \frac{\partial u}{\partial y}$

$$F_x = \int_0^1 \left(p \frac{dh}{dx} + \frac{\partial u}{\partial y} \right) \Big|_{y=h} dx = 0$$

$$= \cancel{ph} \Big|_0^1 - \int_0^1 h \frac{\partial p}{\partial x} \Big|_{y=h} dx + \int_0^1 \frac{\partial u}{\partial y} \Big|_{y=h} dx = 0$$

↑ (**)
↑ (*)

$$\boxed{V_s = \frac{6(1-A)}{4-3A}}$$

where $A = \frac{I_2^2}{I_1 I_3}$ $I_n = \int_0^1 \frac{dx}{h^n}$

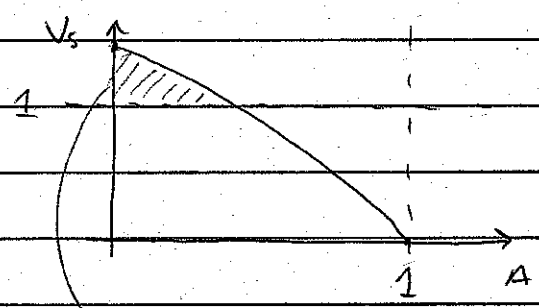
Given shape of foot \Rightarrow speed of "snail"

Properties of A:

Cauchy-Schwartz inequality:

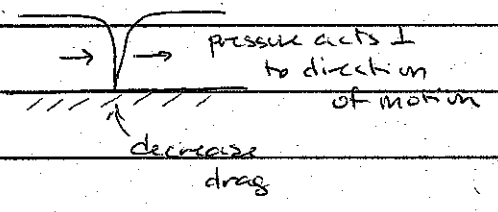
$$I_2^2 = \left(\int h^{-1/2} h^{-3/2} dx \right)^2 \leq \int h^{-3} dx \int h^{-1} dx = I_3 I_1$$

$$\Rightarrow 0 < A < 1$$



snail moves faster than the wave!

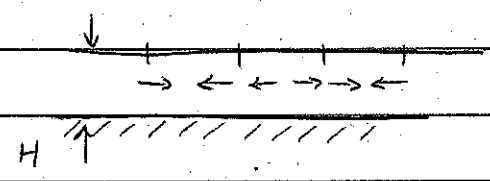
small A \Rightarrow faster snail
"sharp" profiles \downarrow A



[Shelley/
Wilken's
movie]

Comment on lubrication.

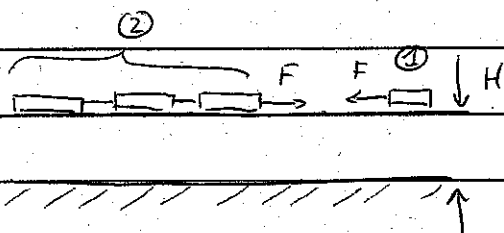
But real snails don't move this way



waves of compression
+ expansion

⑦

Back-of-the-envelope calc



$A =$ area of each pad

$N =$ # of pads

Force balance on ①: $-F = A \frac{v_1 \mu_1}{H}$

Force balance on ②: $F = (N-1) A \frac{v_2 \mu_2}{H}$

Velocity of center of mass: $[v_1 + (N-1)v_2] / N$

$\Rightarrow v_{cm} = \frac{FH}{AN} \left(\frac{1}{\mu_2} - \frac{1}{\mu_1} \right) = v_{cm}$