

LECTURE I

(1)

INTRODUCTION

- What is active matter?

Collection of interacting active particles, each ~~generating~~
self-driven and capable of converting stored
energy in motion / forces, and collectively generating
coordinated motion

- How does it differ from other noneq. system?

drive is local on each unit, not global (field)
or at boundary → reverse energy cascade

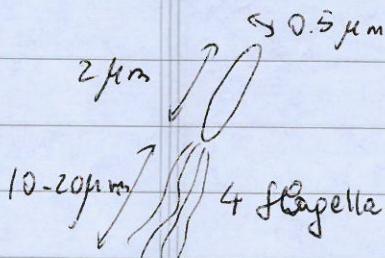
- SP motion is "force free" (\neq sedimentation under gravity)

→ emergent behavior

(not mechanisms of motility)

EXAMPLE OF ACTIVE PARTICLE

E. coli rod-shaped



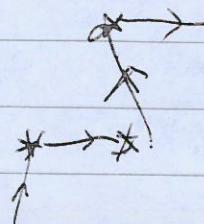
converts chemical energy
into motion via an internal
cyclic transformation

1% gut flora

run-and-tumble
not a conventional RW

$$v_0 \sim 10 - 40 \mu\text{m/s}$$

$$\alpha \sim 1 \text{ s}^{-1}$$



MANY E. coli : swarming, turbulent flow,
pattern formation, biofilms

- not motility mechanisms, but collective behavior
- time \gg cycle (but some recent work on activity and synchronization)

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EXAMPLES ON MANY SCALES → {movies}

- inside a cell : cytoskeleton → cell motility, division, mechanics (Joanny)
- many cells → tissues : mechanics, collective migration, wound healing (Manning)
- fish, birds, people (Toner)
- synthetic ~~micro~~ microswimmer

What do they have in common?

- drive on each unit /symmetry broken locally, breaks TRS
- emergent behavior, order/disorder transition
- [liquid crystalline order] → living &c

{GOALS} Use methods from noneq. stat mech + soft CM

- Which new states of active matter are possible?
- Can we classify behaviors and identify generic properties?
- What do we tune to change from one state to another?

MCM et al, RMP 85, 1143 (2013)

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CLASSIFICATION

Types of orientational order

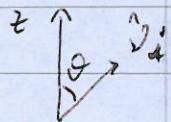
POLAR : bacteria, fish, ...



ferromagnetic
order $\langle \vec{v} \rangle \neq 0$
moving state

O.P. vector

velocity / polarization

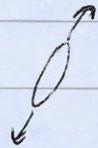


$$\vec{P} = \sum_i \hat{p}_i \delta(\vec{r} - \vec{r}_i)$$

$$P_z \sim \langle w_i g_i \rangle$$

→ Toner

APOLAR : melanocytes, rods, ...



O.P. tensor

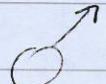
$$Q_{\alpha\beta} = \left\langle \sum_i (\hat{p}_{\alpha i} \hat{p}_{\beta i} - \frac{1}{2} \delta_{\alpha\beta}) \right. \\ \left. \times \delta(\vec{r} - \vec{r}_i) \right\rangle$$

$$Q_{zz} \sim \langle w_i^2 g_i^2 \rangle$$

no state with
mean motion

→ Dogic

SPHERICAL : active colloids



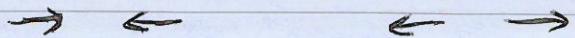
No orientational
order, but

surprising
collective behavior

→ MCM

Role of medium : "dry" vs "wet"

Forces on environment : contractile vs extensile
puller pusher



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VICSEK MODEL OF FLOCKING

1995

Craig Reynolds
1987

inspired by analogy with ferromagnetism

→ flying XY spins

$$\vec{v}_i = v_0 \hat{e}_i$$

θ_i

$$\vec{e}_i = (\cos \theta_i, \sin \theta_i)$$

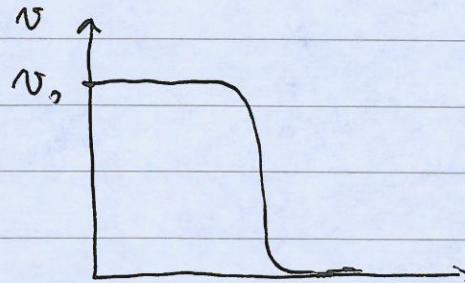
- N point particles
- fixed speed v_0
- align w/neighbors with noisy rules
- overdamped dynamics

~~20 random points~~ ~~20 random points~~ ~~20 random points~~ ~~20 random points~~ ~~20 random points~~

$$\left\{ \begin{array}{l} \vec{r}_i(t + \Delta t) = \vec{r}_i(t) + v_0 \hat{e}_i \Delta t \\ \theta_i(t + \Delta t) = \langle \theta_i(t) \rangle_R + \eta_i(t) \end{array} \right.$$

η_i random #
uniform in $[-\epsilon_{1/2}, \epsilon_{1/2}]$

$$\text{OP } \bar{v} = \left| \frac{1}{N} \sum_i \vec{v}_i(t) \right|$$



• first order

• spontaneous breaking of continuous symmetry in 2d
(\neq Mermin-Wagner) → Toner

21%

Agent or rule-based model → Olems

→ continuum : Toner-Tu model

separation of time scales :

- most fluctuations decay on microscopic time scale
- some are 'slow' ! $\omega(\kappa) \rightarrow 0 \quad A \rightarrow \infty$
decay rate

TUTORIAL : from Langevin dynamics to Smoluchowski

Brownian particle

$$m \frac{d\vec{v}}{dt} = - \underbrace{\zeta \vec{v}}_{\text{mean drag}} + \underbrace{\vec{\eta}(t)}_{\text{random component of effect}}$$

of collisions with fluid atoms

$$\zeta = 6\pi\eta a (3d)$$

$$\langle \vec{\eta}(t) \rangle = 0$$

time scale $\tau = m/\zeta$

$$\langle \vec{\eta}_\alpha(t) \vec{\eta}_\beta(t') \rangle = 2D \delta_{\alpha\beta} \delta(t-t')$$

Gaussian, white

$$\langle |\vec{v}(t)|^2 \rangle \xrightarrow[t \gg m/\zeta]{\Delta \vec{r} = \frac{\vec{v}}{\zeta} \cdot d} \Delta \vec{r} = \langle v^2 \rangle_{th} = \frac{d k_B T}{m}$$

↑ equilibrium

$\Delta = K_B T \zeta$
FD theorem

$$\langle [\Delta \vec{r}(t)]^2 \rangle = 2d \frac{k_B T}{\zeta} \left\{ t - \tau (1 - e^{-t/\tau}) \right\}$$

balance of dissipation and noise

$$t \ll \tau \quad \langle [\Delta \vec{r}(t)]^2 \rangle = d \frac{k_B T}{m} t^2 \quad \text{ballistic}$$

$$t \gg \tau \quad \langle [\Delta \vec{r}(t)]^2 \rangle = 2D dt \quad \text{diffusive}$$

$$D = \frac{K_B T}{\zeta} \quad \text{Einstein}$$

Many particle, interactions : Langevin dynamics hard, not well suited to analytics

→ eq. for probability distribution

overdamped dynamics $t \gg m/\zeta$

$$\sum \vec{v} = \vec{\eta}(t)$$

$$\langle [\Delta \vec{r}(t)]^2 \rangle = 2D dt \quad \text{all times}$$

Derive Eq. for noise-averaged probability distribution

- over damped dynamics
- Ld

$$v = \frac{dx}{dt} = -\frac{1}{\zeta} U'(x) + \gamma(t) \quad \langle \gamma(t) \rangle = 0$$

$$\langle \gamma(t) \gamma(t') \rangle = 2 \Delta \delta(t-t')$$

$\hat{\varphi}(x, t)$ probability density Gaussian, white
but no FD

all t $\int_v dx \hat{\varphi}(x, t) = 1$ conservation law $\Rightarrow \partial_t \hat{\varphi}$ is the

\downarrow divergence of a flux $J = \hat{\varphi} v$
(cf fluid dynamics)

$$\partial_t \hat{\varphi} = -\partial_x v \hat{\varphi}$$

$$\partial_t \hat{\varphi} = -\underbrace{\partial_x \left[-\frac{1}{\zeta} U' \hat{\varphi} \right]}_{L\hat{\varphi}} - \partial_x (\gamma \hat{\varphi})$$

We want an eq. for $\varphi = \langle \hat{\varphi} \rangle$

$$\hat{\varphi}(t) = e^{-\tilde{L}t} \hat{\varphi}(0) - \int_0^t ds e^{-\tilde{L}(t-s)} \partial_x (\gamma(s) \hat{\varphi}(s))$$

$$\partial_t \hat{\varphi} = -L\hat{\varphi} - \partial_x \gamma(t) e^{-Lt} \hat{\varphi}(0)$$

$$+ \partial_x \int_0^t ds \gamma(t) e^{-L(t-s)} \partial_x (\gamma(s) \hat{\varphi}(s))$$

{ $\hat{\varphi}(t)$ only depends
on noise at time
 $s < t$ }

noise average

- assume $\hat{\varphi}(0)$ does not depend on noise $\langle \gamma(t) \hat{\varphi}(0) \rangle = 0$
- $\langle \gamma(t) \gamma(s) \hat{\varphi}(s) \rangle$ Gaussian: only terms with $\gamma \neq 0$
Wick's theorem

$$\langle \gamma(t) \gamma(s) \gamma(s') \rangle \quad \begin{cases} \langle \gamma(t) \gamma(s) \rangle \langle \gamma(s) \rangle \sim \delta(t-s) \\ \langle \gamma(t) \gamma(s') \rangle \sim \delta(t-s') \end{cases}$$

from $\gamma(s) \Rightarrow s' < s$

Smoluchowski equation

but $t > s > s'$ $t-s'$

vanishes

$$\partial_t \gamma = - \nabla_x \left[-\frac{1}{2} \underbrace{\nabla^2 \gamma}_{\text{force}} - \Delta \nabla_x \gamma \right]$$

when FD holds $\Delta = D$

Note: noise was not assumed to be small

Many interacting particles: hierarchy of Smoluchowski eqns. for $\gamma_s(\vec{r}_1, \dots, \vec{r}_s, t)$

$$\mu = \gamma_3 \quad \partial_t \gamma_1 = \vec{\nabla}_1 \cdot \Delta \vec{\nabla}_1 \gamma_1 - \vec{\nabla}_1 \cdot \underbrace{\left[\mu \int d\vec{r}_2 (-\vec{\nabla}_1 \nabla(r_{12})) \gamma_2(\vec{r}, \vec{r}_2, t) \right]}_{\text{interaction force density}}$$

γ_2 couples to γ_3
etc.

molecular chaos

$$\gamma_2 = \gamma_1 \gamma_1$$

$$\underbrace{\left\{ \partial_t \gamma_1 = D \nabla^2 \gamma_1 - \mu \vec{\nabla}_1 \cdot \int d\vec{r}_2 (-\vec{\nabla}_1 \nabla(r_{12})) \gamma_1(r_1) \gamma_1(r_2) \right\}}$$

Non-Gaussian noise \rightarrow higher order gradient terms

MICROSCOPIC \rightarrow HYDRODYNAMICS

Describe large scale dynamics in terms of a small number of continuum fields that are 'slow' \rightarrow field theory

- conserved densities

$$\omega(\mathbf{r}) \rightarrow 0 \quad d \rightarrow \infty$$

- broken symmetry fields

3 ways of constructing dynamical eqs :

- phenomenological (symmetry) \rightarrow TONER
- entropy production (near eq.) \rightarrow JOANNY
- derive by coarse graining microscopic dynamics

EXAMPLE : Vicsek model (continuous time) *

\rightarrow Toner-Tu eqs.

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{\mathbf{e}}_i$$

neglect translational thermal noise

$$\begin{aligned} \frac{d\theta_i}{dt} &= \gamma \sum_j \underbrace{F(\theta_j - \theta_i, \vec{r}_j - \vec{r}_i)}_{\sin(\theta_j - \theta_i) / \pi R^2} + \sqrt{2 D_n} \eta_i(t) \\ &\quad \qquad \qquad \qquad r_{ij} < R \\ &\quad = 0 \qquad \qquad \qquad \text{otherwise} \end{aligned}$$

$$\eta_i \in [-\frac{1}{2}, \frac{1}{2}]$$

$$\text{Now } \Psi = \Psi(\vec{r}, \theta, t)$$

$$\partial_t \Psi = - \vec{\nabla} \cdot (v_0 \hat{\mathbf{e}} \Psi) - D_r \Delta_\theta \Psi$$

$$- \gamma \partial_\theta \int d\theta' \int d\vec{r}' F(\theta', \vec{r}', \vec{r}) \Psi(\vec{r}', \theta') \Psi(\vec{r}, \theta)$$

$$\sin(\theta' - \theta) \delta(\vec{r} - \vec{r}')$$

* E. Bertin, M. Droz, G. Gregoire, J Phys A: Math Th. 42, 445001 (2009)

S. Mishra, A. Basakarau, MCM, PRE 81, 061916 (2010) (banding)

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Continuum fields such as density etc. as moments of ψ

$$\rho(\vec{r}, t) = \int \frac{d\hat{\epsilon}}{2\pi} \psi$$

$$\psi_k(\vec{r}, t) \propto \int \frac{d\theta}{2\pi} e^{ik\theta} \psi$$

$$\rho \vec{P} = \int \frac{d\hat{\epsilon}}{2\pi} \hat{\epsilon} \psi$$

$$\psi_0 = \rho$$

$$\psi_1 = \rho(P_x + i P_y)$$

$$\rho Q_{\alpha\beta} = \int \frac{d\hat{\epsilon}}{2\pi} (\hat{\epsilon}_x \hat{\epsilon}_\beta - \frac{1}{2} \delta_{\alpha\beta}) \psi$$

$$\psi_2 = \rho(Q_{xx} + i Q_{xy})$$

...

...

Eqn for $\psi(\vec{r}, t) \rightarrow$ infinite set of Eqns. $\{\psi_k\}$

$$\partial_t \psi_k + \frac{v_0}{2} \partial_x (\psi_{k+1} - \psi_{k-1}) + \frac{v_0}{2i} \partial_y (\psi_{k+1} - \psi_{k-1})$$

$$\text{decay } \underbrace{= -k^2 D_r \psi_k}_{= -k^2 D_r \psi_k} + \frac{i g k}{2\pi} \underbrace{\sum_s \psi_s F_s \psi_{k-s}}_{F_1 = -i/2, F_{-1} = F_1^*, \text{others } 0}$$

need closure!

$$F_1 = -i/2, F_{-1} = F_1^*, \text{others } 0$$

$$\partial_t \psi_0 + \frac{v_0}{2} (\partial_x - i \partial_y) \psi_1 = 0 \rightarrow \partial_t \rho = -\vec{P} \cdot (v_0 \rho \vec{P})$$

$$\psi_0 \sim \rho \quad \text{conserved field} \quad \checkmark$$

$$\psi_1 \sim \vec{P} \quad \text{order parameter} \quad \checkmark$$

$$-\frac{i}{2} (\psi_1^* \psi_{k+1} - \psi_1 \psi_{k-1})$$

$$\text{Assume } \psi_k = 0 \quad k \geq 3$$

$$\dot{\psi}_2 = 0$$

can be made systematic as an expansion in a small parameter ϵ near ME transition where

$$\rho - \rho_0 \sim \epsilon \quad \psi_1 \sim P \sim \epsilon \quad \partial_t \sim \nabla \sim \epsilon \quad f_2 \sim \epsilon^2$$

[see Peskov et al., EPJ Special Topics 223 1315 (2014)]

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Toner-Tu Eqs of flocking:

$\vec{v} \cdot \vec{\nabla}$ (pressure)

$$\partial_t \vec{v} = - \vec{\nabla} \cdot (\vec{v} \rho \vec{p})$$

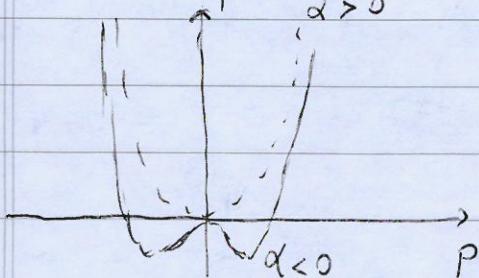
$$\begin{aligned} \partial_t \vec{p} + \lambda_1 (\vec{p} \cdot \vec{\nabla}) \vec{p} &= \left(- [\alpha(\rho) + \beta \rho^2] \vec{p} \right. \\ &\quad \left. + \frac{\lambda_3}{2} \vec{\nabla} \rho^2 + \lambda_2 \vec{p} (\vec{\nabla} \cdot \vec{p}) + k_3 \vec{\nabla}^2 \vec{p} + (k_1 - k_3) \vec{\nabla} (\vec{\nabla} \cdot \vec{p}) \right) \end{aligned}$$

all parameters given in terms of D_r, γ, v_0, g_0

$$\alpha(\rho) = D_r - \frac{1}{2\pi} \gamma \rho$$

$$\beta = \frac{\gamma^2 \rho^2}{32 D_r \pi^2}$$

Dual role of \vec{p}



nonlinear friction

$$- \frac{1}{F} \frac{\delta F}{\delta \vec{p}}$$

$$F = \frac{1}{2} \int_{-\infty}^{\infty} \left\{ \frac{\alpha}{2} \rho^2 + \frac{\beta}{4} \rho^4 \right\}$$

$\lambda_1 = v_0$ if Galileian invariance

substrate \rightarrow nonuniversal parameter

Disordered $|\vec{p}| = 0 \rightarrow$ ordered $\rho_0^2 = -\alpha/\beta$

$$\left\{ \begin{array}{l} \alpha = 0 \\ \rho_c = \frac{2D_r \pi}{\gamma} \end{array} \right.$$

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Banding instability

ordered phase linearly unstable for $\alpha \rightarrow 0^-$ $p_0 \rightarrow 0^+$

$|\delta \vec{p}|$ decay at rate $|\alpha_0| \rightarrow 0$

δg , $|\delta \vec{p}|$ fluctuations unstable along \vec{p}

at a wavelength $\lambda_c \sim (g_c - g_0)^{-3/2}$ (see Refs. on p. 5)

\Rightarrow bands, observed ubiquitously

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Fluctuations about ordered state

$$\delta = \delta_0 + \delta\varphi$$

$$\tilde{P} = P_0 \hat{x} + \delta \tilde{P}$$

$$\tilde{P} = P \hat{P}$$

$$\delta \tilde{P} = \delta P \hat{x} + P_0 \delta \tilde{P}_y$$

spatial variations along x

$$\delta\varphi, \delta P \text{ decouple } \sim e^{iqx}$$

$$\partial_t \delta\varphi = -iq n_0 \delta_P - iq n_0 P_0 \delta\varphi$$

$$\partial_t \delta P = a \delta\varphi - 2i\alpha_0 \delta P - \frac{n_0}{2} iq \delta\varphi$$

generic instability

propagating wave

$$\delta\varphi, \delta P \sim e^{st}$$

$$\operatorname{Re} s = -s_2 q^2 - s_4 q^4$$

$$a \sim -\frac{\partial \alpha}{\partial P}$$

$$s_2 = \frac{n_0^2}{2i\alpha_0} \left[1 - \frac{n_0 \alpha^2 \rho_0^2}{4n_0 i \alpha_0 \beta} \right] \leftarrow \text{unstable even for small } n_0 \text{ near HF-T}$$

no noise : propagating solitary waves
as bands

→ seen in simulation and experiments.

Two comments:

- 1) Method can be used to derive eqs for model with other symmetry, and to include flow
 - SP rods w/ steric repulsion Baskaran + HCM PRL 2008
 - dry "Vicsek nematic" Berthia et al, NJP 2013
 - polar and nematic w/ flow, Liverpool + HCM 2008
in "Cell motility", P. Lenz ed.
 - active polymers : Ahmadi, HCM, Liverpool , PRE 2006
- 3) Eq. for one-particle distribution with ~~no~~ noise ;
 David Dean, J. Phys. A : Math Gen 29, L613 (1996)
 White, Gaussian noise in microscopic dynamics
 → multiplicative noise in ^{noise-principled} ~~the~~ dynamics.

DENSE ACTIVE SYSTEMS : activity and crowding

- Recall Lisa's confluent cell layers
- Show penguin movie

Today's Lecture : activity and exclude volume / steric effects

First → SP dynamics vs Brownian dynamics

- Overdamped Brownian particle ($d=2$)

$$\frac{d\vec{r}}{dt} = \vec{v} = \vec{\gamma}(+) \quad \langle \vec{\gamma}(+) \rangle = 0$$

$$\langle [\Delta \vec{r}(+)] \rangle = 4Dt \quad \langle 2\alpha^{(+)} 2\beta^{(+')} \rangle = 2D\delta_{\alpha\beta}\delta(t-t')$$

$$D = k_B T / 5$$

- SPP

- active colloids
- cells on substrate

• Flyy & MCM PRL 108 235702 (2012)

• Flyy, Henkes, MCM Soft Matter 10, 2132 (2014)

→ Palacci's low density movie + high density

Ajusman San 2005

$$\frac{d\vec{r}}{dt} = N_0 \hat{e} + \vec{\gamma}(+) \quad \hat{e} = (\cos\theta, \sin\theta)$$

$$\frac{d\theta}{dt} = \gamma_r(+) \quad \text{from different rates of H}_2\text{O}_2 \text{ consumption on two sides}$$

$$\langle 2\alpha(+) \rangle = 0$$

$$\langle 2\alpha(+) 2\beta^{(+')} \rangle = 2Dr \delta(t-t')$$

$$[D] = [l^2 t^{-1}]$$

equilibrium : noise $\sim kT$

$$[Dr] = [t^{-1}]$$

$$D \sim a^2 Dr$$

HW : calculate MSD

$$\langle [\Delta \tilde{r}(t)]^2 \rangle = 4D_r t + \frac{2v_0}{D_r} \left[t - \underbrace{\frac{1 - e^{-D_r t}}{D_r}}_{\sim v_0^2 t^2} \right]$$

$$t \ll D_r^{-1} \quad \sim v_0^2 t^2$$

$$t \gg D_r^{-1} \quad \sim \frac{v_0^2}{D_r} t$$

$$\boxed{t \gg D_r^{-1}}$$

$$\boxed{\langle [\Delta \tilde{r}(t)]^2 \rangle \approx 4 \left[D_r + \frac{v_0^2}{2D_r} \right] t}$$

persistence length

$$l_p = v_0 / D_r$$

How does this compare to
run-and-tumble ? (E.coli)

$$\frac{v_0^2}{2D_r} \sim l_p^2 D_r$$

continuous diffusion
at rate D_r

VS

discrete tumble events
mean-time between tumbles
exponentially distributed

$$D_{sp} \sim \frac{v_0^2}{d(d-1) D_r}$$

$$(d-1) D_r \rightarrow \infty$$

tumble rate α

$$D_{sp} \sim \frac{v_0^2}{d \alpha}$$

$$D_{sp} = \frac{v_0^2}{d[\alpha + (d-1) D_r]}$$

(some E.coli mutants
do not tumble)

Differences disappear upon coarse graining.

Apparent only when there is a small-scale structure
in the problem, e.g., traps of size λ ^{large} compared to
run length: ABP trapped at walls.

{ Some numbers }

$$D = \frac{k_B T}{6\pi \eta a}$$

$$k_B T \approx 1.38 \times 10^{-23} \text{ J/K} \quad 300 \text{ K} \approx 5 \times 10^{-21} \text{ J}$$

$$\eta_{H_2O} \approx 10^{-3} \text{ Pa s}$$

$$D_r \approx 0.2 \times 10^{-12} \text{ m}^2/\text{s}$$

$$\approx 0.2 \mu\text{m}^2/\text{s}$$

$$a \approx \mu\text{m} \approx 10^{-6} \text{ m}$$

$$D_{sp} \approx N_0^2 / D_r$$

$$N_0 \approx 10 \mu\text{m/s}$$

$$D_r \approx 10^{-3} - 10^{-4} \text{ s}^{-1}$$

$$D_{sp} \approx 10^8 \mu\text{m}^2/\text{s}$$

$$\alpha \approx 1 \text{ s}^{-1}$$

{ $D_{sp} \gg D$ }

We can neglect translational noise

Both systems :

• particles do not exert torques on each other

nor on a surrounding solvent.

The angular dynamics of each particle is unaffected by that of the others or by interactions

{ Key simplification }

Peclet number

$$Pe = N_0 / a D_r = l_p / a$$

{Effective temperature}

tempting, but...

$$\left. \begin{aligned} \frac{d\vec{r}}{dt} &= \dot{\vec{e}}(\theta) v_0 \\ \frac{d\theta}{dt} &= \gamma_e(t) \end{aligned} \right\} \quad \frac{d\vec{r}}{dt} = \vec{\xi}_{\text{eff}}(t)$$

$$\langle \vec{\xi}_\alpha(t) \vec{\xi}_\beta(t') \rangle = v_0^2 e^{-Dr|t-t'|}$$

$$\rightarrow \frac{v_0^2}{Dr} \delta(t-t') \quad \cancel{\text{for } Dr \rightarrow 0}$$

Non-Markovian noise

$$k_B T_{\text{eff}} = \frac{v_0^2}{2\mu D_r}$$

$$\boxed{P_{\text{ideal}} = g k_B T_{\text{eff}}}$$

$$[D_r] = t^{-1}$$

$$[M] = [m^{-1} t^{+1}]$$

skip

■ ~~PROB~~ Equilibrium : linear response $R = \left(\frac{\partial \langle v \rangle}{\partial f} \right)_{f=0} = \mu = \frac{1}{5}$

$$\text{FD : } \frac{C}{R} = k_B T$$

$$\text{correlation function } C = D = \frac{1}{2} \int_0^\infty dt \langle \vec{v}(t) \cdot \vec{v}(0) \rangle$$

■ Glassy systems : $\frac{C}{R} = k_B T_{\text{eff}}$ a useful concept
sometimes $T_{\text{eff}}(\omega)$

Here :

- Single active particle in an external force, e.g., ~~confined~~^{confining potential V_{ext}} ; equilibrium notion effective only if

$$DV_{\text{ext}} \ll F_{\text{sp}} = v_0 \cancel{\sqrt{5}}$$

or characteristic length set by balance of external and SP force $\sim V_{\text{ext}} \cancel{\sqrt{5}} / v_0 \gg l_p$

Most striking phenomenon \rightarrow MIPS = motility-reduced phase separation

many particles

$$1/D_r \ll T_{\text{coll}} \sim 1/2av_0g$$

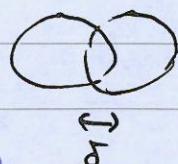
Interacting SPP : only repulsion

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{e}_{\theta_i} + \mu \sum_j \vec{f}_{ij}$$

$$\frac{d\theta_i}{dt} = \gamma_{ri} (+)$$

Repulsive forces :

- soft $\vec{f}_{ij} = -\delta K \vec{r}_{ij}$



- hard spheres
- WCA, LJ, ...

$$\boxed{2d + 3d}$$

Time scales

$$1/D_r$$

$$a/v_0$$

$$1/\mu K$$

$$\tau_c = 1/2av_0\rho$$

$v_0/a \gg \mu K$ pass through

$v_0/a\mu K \rightarrow 0$ athermal packing
 $D_r \rightarrow \infty$ thermal

Phase separation with no attraction \rightarrow MIPS motility-induced

- \Rightarrow movies : • our simulations
• Palaecci clusters

phase separation if $\tau_r > \tau_c$
 $|Peg| \gg 1$

MIPS :

- mean speed of particles along propulsion direction decreases with increasing density (\neq equipartition)
- particles accumulate where they move slowly (not possible in equilibrium systems because speed distribution does not depend on position)

$$v_0 \rightarrow v(g) \approx v_0(1-\lambda g)$$

numerical fits to MSD

Schnitzer, PRE 48, 2553 (1993)

1d run-and-tumble w/ spatially varying speed

$v(x)$ speed of run

α tumble rate

$R(x)/L(x) = \text{density of right/left moving particles}$

$$\begin{cases} \dot{R} = -\partial_x(vR) - \frac{\alpha}{2}R + \frac{\alpha}{2}L \\ \dot{L} = \partial_x(vR) + \frac{\alpha}{2}R - \frac{\alpha}{2}L \end{cases}$$

factor of $\frac{1}{2}$ because

$\frac{1}{2}$ of tumbles are

$R \rightarrow R$ or $L \rightarrow L$

direction switches at

rate $\alpha/2$

$\rho = R+L = \text{density}$

$\sigma = R-L = \text{polarization}$

$J = v\sigma = \text{current}$

$$\partial_t \rho = -\partial_x J \quad \text{conserved}$$

$$\partial_t \sigma = -\partial_x(v\rho) - \alpha\sigma \quad \text{relaxational}$$

$$\text{time } \gg \frac{1}{\alpha} \quad \sigma \approx -\frac{1}{\alpha} \partial_x(v\rho) \quad \text{"adiabatic" approximation}$$

$$\partial_t \rho = -\partial_x \left[-\frac{v}{\alpha} \partial_x v\rho \right]$$

$$\partial_t \rho = -\partial_x \left[\underbrace{-\frac{v^2}{\alpha} \partial_x \rho + \frac{vv'}{\alpha} \rho}_{\text{cf convection-diffusion}} \right]$$

cf convection-diffusion

current

$$J = v\rho - D\partial_x \rho$$

$$\partial_x \rho / \partial_x (v(x)\rho) \approx \partial_x D(x) \partial_x \rho$$

$$D(x) = v^2(x)/\alpha$$

$$V(x) = - \frac{v(x)v'(x)}{\alpha}$$

shift towards regions
of smaller v (- signs)

- $v(x) = \text{constant}$

$$\partial_t p = D \partial_x^2 p$$

only stationary solution is $p = p_*$

- $v(x) \neq \text{constant}$

| | | |
|---|---|--|
| $\begin{array}{c} T \\ \downarrow \\ S_1 \end{array}$ | $\begin{array}{c} T \\ \downarrow \\ S_2 \end{array}$ | <u>steady state</u> $J(x) \equiv \text{const} = 0 \quad \text{no flux}$ |
| $\begin{array}{ c c } \hline S_1 & S_2 \\ \hline \vdash \dashv & \vdash \dashv \\ \hline \end{array}$ | $S_1 v_{th} = S_2 v_{th}$ | $\frac{1}{p} \partial_x p = - \frac{1}{v} \partial_x v$ |
| $\begin{array}{ c c } \hline S_1 v_1 & S_2 v_2 \\ \hline \vdash \dashv & \vdash \dashv \\ \hline \end{array}$ | $S_1 v_1 = S_2 v_2$ | $\left\{ p(x) = p_0 \frac{v(0)}{v(x)} \right\}$ |

This result depends critically on having an upper bound for speed, as opposed to a speed distribution (e.g. M-B) that allows (even if with small probability) arbitrarily large speeds.

Many interacting particles $v \rightarrow v(p)$

$$p \sim \frac{1}{v(p)}$$

feedback yields
phase separation

Continuum Model

ρ conserved

\vec{p} no phase transition

Non interacting particles

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{e}_i + \vec{\gamma}_i(t)$$

$$\frac{d\vec{p}_i}{dt} = \vec{\gamma}_{Ri}(t)$$

$$\partial_t \psi(r, \theta, t) = -\vec{\nabla} [v_0 \hat{e}_4 - D \vec{\nabla} \psi] + D_r \partial_\theta^2 \psi$$

$$\partial_t \rho = -\vec{\nabla} \cdot [v_0 \rho \vec{p} - D \vec{\nabla} \rho]$$

$$\partial_t \vec{p} = -D_r \vec{p} - \frac{v_0}{2} \vec{\nabla} \rho + \kappa (D \vec{\nabla} \rho)$$

interactions here are repulsive steric effect.
do not yield alignment, but reduce motility

$$v_0 \rightarrow v(\rho) = v_0(1 - \lambda\rho)$$

λ depends on pair correlation function

higher probability of finding particles ahead of you than behind

Clustering of inelastic systems arise from combining the dynamics of a conserved field (density) with non-conserving noise. This gives $S(k) \sim 1/k^2$, like GNF in ordered state

$$\partial_t \tilde{g} = -\vec{\nabla} \cdot [v(\phi) g \vec{p}] + D \nabla^2 g$$

$$\partial_t \tilde{p} = -D_r \tilde{p} - \frac{1}{2} \vec{\nabla} [\tilde{p} v(\phi)] + O(D^2)$$

$\left\{ t \gg 1/D_r \right\}$

$$\tilde{p} \approx -\frac{1}{2D_r} \vec{\nabla} [\tilde{p} v(\phi)]$$

quasi-thermal limit

$$\partial_t g = \vec{\nabla} \cdot Q(g) \vec{\nabla} g$$

$$Q(g) = D + \frac{v'(g)}{2D_r} + \frac{v g N'}{2D_r}$$

$$N(g) = N_0(1-\lambda g)$$

$$Q_{eff} = D + \frac{v_0^2}{2D_r} (1-\lambda g)(1-2\lambda g)$$

minimum Pe
required for
phase separation

$Q_{eff} < 0$ spinodal phase separation

$\left\{ \text{Kinetic estimate of } \lambda \right\}$

$$\tau_c \sim (2a N_0 g)^{-1} \quad \text{mean free time}$$

$$v(g) \sim v_0 (1 - \tau/\tau_c) \quad \tau \sim \text{mean delay caused by collisions}$$

- $\tau_1 \sim a/v_0$ escape by traveling a while maintaining orientation

- $\tau_2 \sim 1/D_r$ must rotate to escape

$$\frac{1}{\tau} = \frac{1}{\tau_1} + \frac{1}{\tau_2} \quad \text{faster mechanisms wins (back)}$$

finite D_r : retain dynamics of \vec{p} and examine stability of homogeneous state $p = p_0, \vec{p} = 0$
by letting $p = p_0 + \delta p$

$$\vec{p} = \delta \vec{p}$$

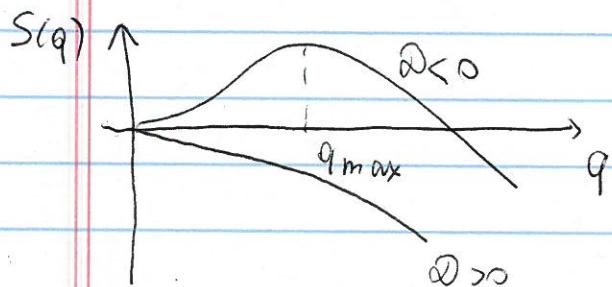
$$\delta g(\vec{r}, t), \delta \vec{p}(\vec{r}, t) \sim e^{s \cancel{at} + i \vec{q} \cdot \vec{r}}$$

$$(\partial_t + D q^2) \delta g_q + i v(g_0) \vec{q} \cdot \vec{p} = 0$$

$$(\partial_t + D_r \sqrt{+kq^2}) \delta \vec{p} + \frac{1}{2} (v' + g_0 v') i \vec{q} \delta p = 0$$

small q : mode

$$S(q) = -q^2 D(p_0) + q^4 B$$



$$q_{\max} \sim \sqrt{-\frac{D}{2kD}}$$

This result can also be interpreted in the context of a Landau-type HFT (ignoring gradient terms, i.e., $v(g(r))$ is local).

In fact one can map a SPP with $v(g)$ onto a Landau-like HFT of a system of attractive particles undergoing liquid-gas phase separation.

Pressure

- force/area on walls of container
- thermodynamics : $p = -\left(\frac{\partial F}{\partial V}\right)_N \Rightarrow$ eqn. of state
- hydrodynamics : $p = gkT + \frac{1}{6V} \left\langle \sum_{i \neq j} \vec{r}_{ij} \cdot \vec{F}_{ij} \right\rangle$
or virial

Ideal gas of SP particles :

$$\vec{r}_i = \underbrace{\sum v_0 \hat{e}_i}$$

$$\dot{\vec{r}}_i = \gamma_i(t) \quad \rightarrow \text{SP force } \vec{f}_i^{\text{SP}}$$

$$\text{or } \frac{1}{3V} \left\langle \sum_i \vec{r}_i \cdot \vec{f}_i \right\rangle$$

virial

$$P_{\text{act/swim}} = \frac{1}{2A} \left\langle \sum_i \vec{r}_i \cdot \vec{f}_i^{\text{SP}} \right\rangle$$

$$= \frac{1}{2A} \int_{-\infty}^t dt' \left\langle \sum v_0 \hat{e}_i(t') \cdot \sum v_0 \hat{e}_i(t) \right\rangle$$

$$P_{\text{act/swim}} = \frac{\rho v_0^2}{2\mu D_r} (1 - e^{-D_r t}) \xrightarrow{t \rightarrow \infty} \frac{\rho v_0^2}{2\mu D_r} = \rho k T_{\text{eff}}$$

in a container

$$t \sim L/v_0$$

$$P_{\text{swim}}(t \sim L/v_0) \sim \begin{cases} \rho k T_{\text{eff}} & \text{if } L \gg \ell_p \\ \frac{\rho v_0 L}{2\mu} & L \ll \ell_p \end{cases}$$

Detailed calculations have shown

$$P_{\text{sink}} = \frac{\rho v_0 n(g)}{2 \mu D_r}$$